UNDERSTANDING TRUCK-MOUNTED HYDRAULIC SYSTEMS
Muncie Power Products is dedicated to providing quality products and services that will satisfy the needs and expectations of our customers. We are committed to the continual improvement of our products and processes to achieve our quality objectives, minimize costs to our customers and realize a reasonable profit that will provide a stable future for our employees.
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UNDERSTANDING TRUCK-MOUNTED HYDRAULIC SYSTEMS

This booklet will attempt to answer questions and provide insights into how a truck-mounted, or mobile, hydraulic system operates, what components make up the system, how they work, and why they sometimes fail to perform as expected. Our frame of reference is that of a leading manufacturer and distributor of hydraulic power systems and components. As such, the information gathered here represents the combined experience of many knowledgeable professionals over many years.

Our intent is to consider the entire system and its function as well as the individual components. While the individual design may vary, the basic functions and terminology of all systems remain the same. The laws of physics still apply and most malfunctions are both predictable and preventable.

While some systems may not be exposed to extreme temperatures or long duty cycles, generally speaking, truck-mounted systems operate under conditions more rigorous than stationary hydraulic systems. Integrating hydraulics with the capabilities and limitations of the truck engine, transmission, and power take-off is paramount. Remember also that truck-mounted hydraulic systems differ from industrial systems in another important way—they have a driver.

Because hydraulic components experience stress from high pressures, it is important that they be properly installed. It is important to use torque wrenches properly and to apply torque evenly to avoid uneven stresses and prevent leaks.

We have attempted to publish facts about how components work, how to troubleshoot when they don’t, and what causes some of the predicaments you must correct. If you still have questions about your equipment’s performance, consult the manufacturer’s service manual for operating cycle times, pressures, oil recommendations, etc., particularly before replacing components.

To assist in determining system requirements and selecting proper components, a complete page of hydraulic and mechanical formulas has been provided on page 38 of this booklet.

Muncie Power Products provides two other resources: our website and our M-Power Software. The website, munciepower.com, contains information on Muncie Power’s complete product line, service and installation manuals, authorized distributor locations, and much more. It also serves as a launching point for our web-based M-Power. Within M-Power you can make power take-off and pump selections, perform hydraulic and mechanical calculations, view service parts drawings, and cross over competitor model numbers.

Also, while visiting the Muncie Power’s website, be sure to look in the training area for information on the product training classes and seminars offered as well as information about the online training, M-Power Tech.

Finally, Muncie Power makes available to you one other very important resource—our people. Muncie Power’s customer service managers are ready to share their knowledge with you and are just a toll-free phone call away.

Call 800-367-7867 (FOR-PTOS) for assistance in component selection or refer to system troubleshooting on page 36 of this manual.
SECTION 1: PRINCIPLES OF HYDRAULICS

Truck-mounted hydraulic systems, regardless of their application, have in common the basic components and operating principles of any hydraulic system. They utilize a power source, reservoir, pump, directional control valve, and actuators to move and control fluid in order to accomplish work.

In every hydraulic circuit, we start with mechanical power in the form of a rotating shaft, convert it to hydraulic power with the pump, direct it with a valve to either a cylinder or a motor, and then convert it back to mechanical power. We do this because, while in the form of fluid power, we can direct and control the application of force.

All hydraulic applications are based on flow and pressure requirements. Flow, expressed in gallons per minute (GPM), determines the speed at which a hydraulic cylinder extends or a hydraulic motor turns. Flow is produced by the pump. Pressure, expressed in pounds per square inch (PSI), determines the amount of force exerted. Pressure occurs when flow meets resistance.

Pressure is not produced, but is tolerated by the pump. The combination of flow and pressure required by a hydraulic system determine the operating horsepower (HP). This horsepower requirement is determined by the formula:

\[ HP = \text{GPM} \times \text{PSI} \div 1,714 \]

Example: A hydraulic system requires 12 GPM at an operating pressure of 2,000 PSI. The hydraulic horsepower requirement is:

\[ 12 \times 2,000 \div 1,714 = 14 \text{ HP} \]

Pascal’s Law

The basic principle governing hydraulics goes back to a seventeenth century French mathematician and philosopher, Blaise Pascal. Pascal’s Law states that a pressure applied to a confined liquid is transmitted instantly, equally, and undiminished, at right angles, to all surfaces of the container. Since oil is virtually non-compressible (only 0.5% per 1,000 PSI) any force applied to one end of an oil-filled tube or hose will be instantly transmitted to the other end.

Both flow and pressure are required to accomplish work.

It is important, from a troubleshooting standpoint, to remember this differentiation between flow and pressure. Flow determines actuator speed and pressure determines system force. A hydraulic system that will not lift a load is likely experiencing a pressure related problem. One that will perform work, only slowly, is likely experiencing a flow related problem.

**NO FUNCTION = no pressure**

**SLOW FUNCTION = low flow**

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**FOUR IMPORTANT HYDRAULIC LAWS**

I. **PASCAL'S LAW**: A pressure applied to a confined fluid at rest is transmitted adiabatically (without gain or loss of heat) with equal intensity throughout the fluid and to all surfaces of the container. THESE LAWS WILL AFFECT BEHAVIOR OF AIR, WHICH CAUSES FAILURE. THEY HELP EXPLAIN THE PHENOMENA OF CAVITATION & AERATION.

II. **BOYLE’S LAW**: Under constant temperature, the absolute pressure of a fixed mass of gas varies inversely with its volume.

III. **CHARLES’ LAW**: Under constant pressure, the volume of a fixed mass of gas varies directly with the absolute temperature.

IV. **HENRY-DALTON’S LAW**: The amount of air that can be dissolved in a system is directly proportional to the air pressure above the fluid.
Four pressures

Remember, there are four pressures at work in a hydraulic system:

**Atmospheric** pushes the oil from the reservoir to the pump inlet. Pumps are designed to be fed, not to draw oil. For this reason, it is desirable to place the reservoir directly above the pump inlet. This is also why we refer to the pump's inlet port rather than its suction port. Atmospheric pressure at sea level is 14.7 PSI and approximately ½ PSI is lost with each 1,000 foot rise in elevation. In practical terms, it may be necessary to utilize larger diameter inlet hoses and pay closer attention to reservoir placement in high altitude locations like Denver, Colorado, or Salt Lake City, Utah.

**Neutral system** is the resistance to flow posed by the system itself as measured at the pump outlet when all control valves are in the neutral position. Every component, hose, and fitting that the oil must flow through to get from the pump outlet to the return port of the reservoir adds to the neutral system pressure. This is sometimes referred to as ΔP (Delta-P) or parasitic pressure. It takes away from the work than can be performed by the actuator and transforms the wasted energy into system heat. Systems with high neutral pressure run hotter and wear out sooner. Ideally, neutral pressures should be kept under 300 PSI. In our troubleshooting experience, we have observed neutral system pressures as high as 900 PSI.

**Pump operating** should be self-explanatory. This is the pressure required to accomplish work (to extend the cylinder or turn the hydraulic motor) and is measured at the pump outlet. As measured at the pump, it is the actuator working pressure, in addition to the system pressure drop. If 1,500 PSI is required to run a hydraulic motor and the system pressure drop is 500 PSI, the operating pressure measured at the pump will be 2,000 PSI.

**Relief pressure** is the pressure at which the system relief valve will open and bleed flow back to the reservoir until the system pressure diminishes. Typically, the relief pressure will be set approximately 15% above the system working pressure. Thus, a system designed to operate at 2,000 PSI would have its relief valve set for 2,300 PSI.

### HOW MUCH HYDRAULIC PRESSURE CAN BE EXPECTED IN A TRUCK-MOUNTED HYDRAULIC SYSTEM?

There are those who believe that system operating pressure is determined by a setting or an adjustment on a relief valve. Actually, as we will see, hydraulic pressure is created or limited by several factors:

- **load to be moved**
- **displacement of the hydraulic motor, or the area of the cylinder’s piston**
- **mechanical efficiency of the design**
- **hydraulic efficiency of the design**

We will use the number 231 throughout our discussion of hydraulic system components. 231 is the number of cubic inches of liquid, for our purposes oil, contained in one gallon. Hydraulic component manufacturers rate pumps and motors according to their cubic inch displacement (CID). Just as we discuss auto engines in terms of cubic inches, we also specify and compare hydraulic pumps in terms of CID. In pump displacement terms, we are referring to the amount of oil flow a pump produces with each complete rotation of its input shaft. Thus, a 4 cu.in. pump will, with each shaft rotation, move 4 cu.in. of oil from its inlet.
to its outlet. What does this mean in terms of GPM, the measurement we are most accustomed to? If our application requires a flow rate of 20 GPM we must turn the input shaft of our 4 cu.in. pump at a speed of 1,155 revolutions per minute (RPM).

\[ 20 \text{ GPM} \times 231 = 4,620 \text{ (cu.in. in 20 gal.)} \]
\[ 4,620 \div 4 \text{ cu.in. (pump displacement)} = 1,155 \text{ RPM} \]

We will also use the number 231 in our discussion of hydraulic reservoirs, cylinders, and motors.

**Hydraulic system efficiency**

No hydraulic system is 100% efficient. This is because no individual hydraulic component is 100% efficient. There are two mechanical obstacles that must be overcome: friction and internal leakage. Both, which are unavoidable, take away from the overall efficiency of the components and, therefore, the entire system.

It has been calculated that hydraulic systems that utilize cylinders as their actuators, when new, are approximately 85% efficient, whereas hydraulic motor systems are approximately 80% efficient. This has two effects: One, pump input horsepower requirements will exceed output horsepower by a factor equal to the inefficiency. Two, the horsepower lost through inefficiency will be converted to heat.

Gear pumps, for example, when new, have a volumetric efficiency of approximately 94%. This means that for every 10 gallons of oil that is drawn in through the inlet port, 9.4 gallons will exit through the outlet. The remaining .6 gallons, more or less, will slip past the tips of the gear teeth. What happens when components leak internally—heat. Inefficiency manifests itself as heat. The greater the system inefficiency, the higher the heat. As time passes, the components wear and become less efficient, hydraulic systems operate slower and generate more heat.

**Open and closed center hydraulic systems**

As we have discussed, to perform work hydraulically requires the presence of two conditions: flow and pressure. If either is eliminated, work stops. Alternately, if either can be controlled, we can control hydraulic work. This has lead to two designs of hydraulic systems: open center and closed center.

**Open center**

The term open center describes both the type of hydraulic circuit and, literally, the construction of the directional control valve. In an open center system, flow is continuous and pressure is intermittent. With the pump turning, flow is produced and is routed through a central passageway in the directional control valve back to tank. When a spool in the directional control valve is stroked, flow is directed toward a load resulting in pressure. Once the pressure exceeds the load, the load moves.

**Closed center**

Likewise, the term closed center describes both the type of hydraulic circuit and the construction of the directional control valve. In a closed center system, flow is intermittent and pressure is continuous. With the pump turning, only enough flow is produced to maintain a standby pressure at the directional control valve and to keep the pump lubricated. When a spool is stroked, a pathway for flow is revealed and, simultaneously, pressure signal information is delivered to the pump from the directional control valve, signaling the pump to produce flow.

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**Volumetric efficiency**

The actual output flow of a pump as compared to its theoretical output based on cubic inch displacement.

\[ \text{VE} = \frac{\text{Actual output}}{\text{Theoretical output}} \]

**Mechanical efficiency**

A measure of a pump’s internal power losses as a percentage of the input power. (Any internal friction—bearings, seals, etc.—will result in a power loss.)

**Overall efficiency**

The efficiency of the pump when the volumetric and mechanical efficiencies are factored.
SECTION 2:
THE PRIME MOVER

The prime mover supplies the mechanical power to drive the hydraulic system. In the mobile hydraulics industry, the prime mover we are most familiar with is the truck engine. The truck engine is frequently used to provide power through a power take-off (PTO), through belts from the crankshaft pulley, or directly through a tubular driveshaft assembly. On some high horsepower systems an auxiliary, or pony engine, might be used. In any case, the prime mover must be capable of providing the horsepower necessary to power the hydraulic system. Refer to the hydraulic horsepower formula on page 3.

Power take-offs
The original PTOs were single gear models with a gear that slid into and mesh with a transmission gear, resulting in output shaft rotation. Single gear PTOs are limited by their speed and horsepower capabilities. You will find them used primarily on small, single axle dump trucks and agricultural hoists. Most single gear PTO’s have become obsolete.

Double or triple gear, PTOs, found on dump trucks, refuse vehicles, wreckers, aerial bucket trucks, tank trucks, and truck-mounted cranes, are the most widely used type of PTO because of their versatility. These types of PTOs can be engaged by cable, air, electric solenoid, or mechanical levers. They offer a wide variety of output shafts and mounting flanges, which allow for direct coupling of hydraulic pumps from major manufacturers. PTO output shaft speeds can be faster or slower by changing the internal gear ratio of the PTO.

The newest design in PTOs is the clutch shift type. These models engage by means of friction disks rather than sliding gears. Clutch type PTOs are commonly used on refuse, utility, and emergency equipment—garbage trucks, aerial bucket trucks, and fire/rescue vehicles.

We will not attempt to go into PTO selection in this text. Suffice to say that when a PTO is utilized as the source of power for the hydraulic system, it must meet the torque, horsepower, and speed requirements of the system. For more detailed information on PTO types, selection, and troubleshooting see our training guide on “Understanding Power Take-off Systems.”

Engine crankshaft driven
Many refuse and snow control vehicles utilize a front-mounted hydraulic pump driven by a tubular driveshaft assembly from the harmonic balancer of the engine. This live power arrangement has the advantage of providing full engine torque on high-demand applications while eliminating the cost of the PTO. The disadvantage to this type of installation is in the requirement to raise, or core, the radiator to allow passage for the driveshaft; extend the front frame rails; and fabricate a mounting bracket for the pump.
Drivelines used for this application must be of the balanced, tubular type capable of transmitting high torque loads. The Spicer 1310 series or its equivalent is commonly specified. Solid bar stock should never be used in crankshaft drive applications.

Another important consideration is driveshaft angularity. Not only is it necessary to keep the angle shallow—generally less than 7° F—but also to keep the pump input shaft parallel to the engine crankshaft within 1½°. Likewise, the yokes on each end of the shaft must be in phase, or aligned with each other. Failure to address any of these requirements will result in driveshaft vibration and damage to the pump.

**Auxiliary engines**

Auxiliary engines, gasoline or diesel, are typically used only in applications requiring full engine horsepower and torque. In truck-mounted applications this would include such things as large vacuum pumps and concrete pumps. Usually, one or more hydraulic pumps are coupled to the engine's output shaft.

**Belt-driven pumps**

Belt-driven pumps, or “clutch pumps,” are popular power sources for applications such as wreckers and bucket trucks. They also represent an alternative to a PTO system on vehicles without PTO apertures or where access to the transmission PTO aperture is obstructed. The clutch pump is belt-driven from the crankshaft pulley through an electric clutch similar to that found on an automobile air conditioner compressor.

One important consideration in clutch pump applications is the horsepower limitation of the engine belts. Dual ½ inch, automotive type belts can transmit about 7 HP. Most applications will utilize two v-belts or a poly-v type belt to drive the pump. This belt limitation (and available space limitations) prohibits the use of large displacement pumps (greater than 2½ cu.in.) in clutch pump applications. Serpentine belt drives can deliver horsepower comparable to that of two v-belts.

Changes in truck design and cramped engine compartments present challenges to clutch pump manufacturers. However, clutch pumps remain a popular option for hydraulic applications requiring flows of up to 15 GPM.

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**Note:** Solid shafting is not recommended for continuous operating speeds above 1,000 RPM.

**Belt-driven Clutch Pump**

Proper belt alignment and tension are critical to clutch pump performance.
SECTION 3: PUMPS

Hydraulic pumps take the mechanical energy of the prime mover (a turning force) and convert it to fluid energy in the form of oil flow. As previously discussed, we normally refer to this oil flow in terms of gallons per minute (GPM). It is this flow rate which determines the speed at which a system will operate.

If you have the manufacturer’s specifications for the hydraulic system, they should state the operating flow (GPM/LPM) and pressure (PSI/BAR) requirements. There may also be a suggested make and model for the pump. As far as the hydraulic system is concerned, any pump which will meet the flow and pressure requirements will work equally well. Some may be more efficient. Some may look different. The real cost may not be in the purchase price but in the cost of operating and maintaining the system over its life.

Pumps may be of either a uni-rotational or bi-rotational design. Uni-rotational pumps are designed to operate in only one direction of shaft rotation, while bi-rotational pumps can operate in either direction. Uni-rotational pumps are distinguishable in that the inlet and outlet ports are different sizes, with the inlet being the larger. Some bi-rotational pumps have two input shafts to match the rotation of the driveshaft. Bi-rotational pumps also tend to have equally sized ports since either can be the inlet or outlet, depending on rotation.

NOTE: As a rule of thumb, if the pump is PTO driven by a PTO on a manual transmission, the input rotation will be left-hand (CCW). If PTO driven on an automatic transmission it will be right-hand (CW) rotation. Ford automatics are the exception. Front-mounted, crankshaft driven pumps will be left-hand rotation.

Positive and variable displacement pumps

Three types of hydraulic pump construction are typically found in mobile hydraulic applications: gear, piston, and vane.

Gear pumps

Gear pumps are the most common design in use for truck-mounted hydraulic systems. Gear pumps are relatively inexpensive, have few moving parts, are easy to service, and are generally more tolerant of contamination than other designs.

Gear pumps are fixed, or positive, displacement pumps. That is, they produce the same volume of flow with each complete shaft rotation. The types of systems in which gear pumps are generally used are referred to as open center systems. Open center systems are those which allow oil to flow through the open center core of the directional valve and back to reservoir under low, return pressure when it is not being directed to a work function. Gear pumps can only be used in closed center systems if special unloading valving is utilized.

Gear pumps operate by trapping oil in the areas between the teeth of their two gears and the body of the pump, transporting it around the circumference of the gear cavity, and forcing it through the outlet port as the gears mesh. A small amount of pressurized oil is allowed behind brass alloy thrust plates, often referred to as wear plates, at each end of the gear set, pushing them tightly against the gear ends to improve pump efficiency.

Gear pumps are rated in terms of their CID, maximum pressure rating, and maximum input speed limitation.
Muncie Power gear pumps are available in displacements from ½ cu.in. to 14 cu.in. Pump manufacturers use a rating speed to describe their pumps. This allows them to describe their pump in GPM terms most users are accustomed to. A manufacturer using 1,000 RPM as its rating speed would, for example, refer to their 7 cu.in. pump as a 30 GPM pump (7 cu.in. × 1,000 ÷ 231 = 30.3 GPM). A manufacturer using 1,200 RPM as their rating speed would refer to the same 7 cu.in. pump as a 36 GPM pump (7 cu.in. × 1,200 ÷ 231 = 36.36 GPM).

**Caution: Not all pump manufacturers use the same rating speed.** Some use 1,000 RPM, some use 1,200, and some use 1,800. Care must be taken in comparing or replacing pumps from different manufacturers. You do not want to sell a pump too large or small for their application because you did not make an accurate comparison. If possible, make your determination based on CID comparisons or the original equipment specification.

All pumps, regardless of design, have a maximum pressure rating. This is the highest pressure at which the pump was designed to operate. It is not the pressure that the pump encounters every time it is operating. The maximum operating pressure rating is affected by many variables including shaft diameter, bearing loads, body composition, port type, and port size. One major factor that affects pressure ratings of gear pumps is the distance between the front and rear bearings that support the pump’s gears. The greater the unsupported length, the lower the maximum pressure rating.

A pump’s maximum operating speed is based primarily on the limit at which the rotating gears can fill the gear cavity before cavitation begins, although bearing type and the quality of the hydraulic oil can also be factors. Oftentimes, this relates to port diameter and location. It can also be affected by hose size, reservoir location, and oil viscosity. Operating at excessive speeds can result in cavitation and or heat damage. More on cavitation later.

Interestingly, gear pumps also have a minimum speed limitation. Gear type pumps are generally most efficient in the upper third of their operating speed range. Pumps turned slowly are less efficient than those turned faster. Operating below the minimum RPM results in excess heat generation, which can damage seals and wear plates. Generally speaking, gear pumps should not be operated at input shaft speeds under 1,000 RPM. The chart below shows a typical performance chart for a gear pump. Notice that at a constant pressure the pump’s volumetric efficiency will increase as pump shaft speed increases. You will also notice that at a constant speed efficiency will decrease as pressure increases. Changes in either speed or pressure will affect a gear pump’s volumetric efficiency. Pumps operated in the upper end of their speed range are more efficient than those operated in the lower end. Keep this in mind when selecting a PTO.

### PUMP OUTPUT FLOW BASED ON CID THEORETICAL

<table>
<thead>
<tr>
<th>DISPLACEMENT</th>
<th>SHAFT SPEED (RPM)</th>
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<tbody>
<tr>
<td></td>
<td>1,000</td>
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<tr>
<td>1</td>
<td>4</td>
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<tr>
<td>2</td>
<td>9</td>
</tr>
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<td>13</td>
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<td>8</td>
<td>35</td>
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<tr>
<td>9</td>
<td>39</td>
</tr>
</tbody>
</table>

Formula: GPM = CID × RPM ÷ 231

### SAE MOUNTING/SHAFT SIZES

<table>
<thead>
<tr>
<th>SAE</th>
<th>PILOT</th>
<th>BOLT CIRCLE</th>
<th>SHAFT SIZE</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>3.25&quot;</td>
<td>(2) 4.188&quot;</td>
<td>.624&quot;</td>
</tr>
<tr>
<td>B</td>
<td>4&quot;</td>
<td>(2) 5.75&quot;</td>
<td>.875&quot; - 13 spl.</td>
</tr>
<tr>
<td></td>
<td>4&quot;</td>
<td>(4) 5&quot;</td>
<td>.875&quot; - 13 spl.</td>
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<td>BB</td>
<td>4&quot;</td>
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<td>1&quot; - 15 spl.</td>
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<td>C</td>
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<td>1.25&quot; - 14 spl.</td>
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<td></td>
<td>4&quot;</td>
<td>(4) 6&quot;</td>
<td>1.25&quot; - 14 spl.</td>
</tr>
</tbody>
</table>
Piston pumps

Piston type pumps are frequently used where high operating pressures are required. Piston pumps will, as a rule, tolerate higher pressures than gear pumps of comparable displacements. Truck-mounted cranes frequently utilize piston pumps. The downside comes in the form of higher initial cost, lower contamination resistance, and higher complexity. With more moving parts, closer tolerances, and stricter filtration requirements, piston pumps require more sophistication on the part of the equipment designer and service technician.

A piston pump consists of a cylindrical block containing pistons which, as they move in and out, draw oil from the supply port and force it through the outlet. The length of the piston’s stroke is determined by the angle of a swash plate which the slipper end of the piston rides against. The cylindrical block, containing the pistons, rotates with the pump’s input shaft while the swash plate remains stationary. The total volume of the pump’s cylinders determines the pump displacement.

Piston pumps are available in both fixed and variable displacement designs. A fixed displacement piston pump has a non-adjustable swash plate angle and, like a gear pump, its output flow is directly proportional to input shaft speed. This type of piston pump, like the gear pump, is used in open center hydraulic systems.

In some applications—snow and ice control vehicles for example—the hydraulic flow requirements will vary based on operating conditions and it may be desirable to vary system flow without varying engine (pump input) speed. In these applications, a variable displacement piston pump is specified. With this design, the swash plate is not fixed and its angle is adjusted, through a compensator, by a pressure signal from the directional valve. If more flow is required, the swash plate angle changes to create a longer piston stroke thereby increasing the pump displacement. Variable displacement pumps are used in closed center systems. In these systems there is no excess flow—or lost hydraulic horsepower—because the swash plate angle decreases as the flow requirement diminishes. Variable displacement piston pumps may be either pressure compensated, flow compensated, or both pressure and flow compensated.

A pressure compensated system is one which adjusts the swash plate angle (pump displacement) to maintain a specified pressure regardless of changes in system flow.

A flow compensated system adjusts the swash plate angle to maintain a constant margin pressure as flow requirements change.

A system with a combination of pressure and flow compensation is often referred to as a load sensing system. Many snow and ice control vehicles utilize this type of system.

Vane pumps

Vane pumps, once common on utility vehicles (aerial buckets and ladders), are not as frequently found on mobile (truck-mounted) hydraulic systems today. The primary reason can be traced to the wide acceptance and availability of gear type pumps and the greater equipment control provided by variable displacement piston pumps. Muncie Power does not carry vane pumps.

Vane pumps work similar to gear pumps in that as the input shaft rotates it causes oil to be picked up between vanes and transported to the pump’s outlet side. However, there is only one set of vanes, as opposed to a pair of gears, on a rotating cartridge in the pump housing. The area between the vanes increases on the inlet side of the pump and decreases on the outlet. This change in area results in the oil being allowed in through the supply port and expelled through the outlet as the vane cartridge rotates.
Dump pumps

The most recognizable truck pump is the dump pump. The dump pump, as we know it today, was introduced over 50 years ago and little has changed since, although the newest design offers larger ports and a more efficient gear design. This pump, common on dump trucks from tandem axle to dump trailers, is essentially a gear pump of slightly more than 6 CID with an integral three-position, three-way directional control valve, and pressure relief assembly. The most important thing to keep in mind about these pumps is that they were designed specifically for one application: dump trucks—hence the name. They are not suitable for other common trailer applications like live floor and ejector trailers. Narrow internal paths make them unsuitable for continuous duty applications due to the likelihood of excessive heat generation. Dump pumps also have maximum pressure ratings that may fall below the requirements of some live floor applications. For applications involving both dump and live floor trailers, use the Muncie Power Combo Kit II System which utilizes a high pressure, continuous duty pump and separate high volume control valve with a two-stage relief assembly.

Dump pumps are commonly direct-coupled to the PTO. Weighing 70 lbs., it is vital that direct-coupled pumps be rigidly supported via an installer-supplied bracket to the transmission case. This bracket should be a four-point (two-pump/two-transmission) type. Dump pumps provide extended assembly studs to use as attachment points. Refer to the PTO installation manual for additional information and design suggestions.

The most important consideration in dump pump selection is two-line vs. three-line installation. This refers to the number of hoses used to plumb the pump. Two-line systems utilize a common inlet and return hose and are common on trucks that simply dump, rather than spread, materials. Three-line systems are equipped with a dedicated return hose and are preferred if the truck will be used for spreading—applying gravel to a roadbed for example. A dump pump can easily be converted from two- to three-line by inserting an inexpensive sleeve into its inlet port, uncapping, and plumbing the return port. The sleeve blocks an internal path and neutral/return oil is directed back to tank via the return port. There is one special concern: the third (return) line must be positioned below the tank’s oil level to prevent loss of prime and subsequent pump aeration damage.

There are multiple benefits of a three-line installation over a two-line. The primary benefit is one of efficiency. The third line allows an unobstructed return path to reservoir resulting in faster cycle times. The second benefit is system protection should an operator inadvertently leave the PTO in
gear—and the pump turning—while traveling down the road. The third is that the dedicated return line allows for the installation of a return line filter to remove contaminates; an important consideration, especially if trailers are frequently switched between tractors.

**Pumps for refuse vehicles**
Both Dry Valve and Live Pak™ pumps conserve fuel while in the off mode, yet provide full flow when work is required. Both are based on standard gear pump designs with additional, special valving incorporated.

**Dry valve pumps**
Dry Valve pumps are large displacement (6-9 cu.in.) front crankshaft driven pumps used primarily on refuse equipment. Dry valve pumps utilize a special plunger-type valve in the pump inlet port to restrict flow in the OFF mode and allow full flow in the ON mode. This lowers horsepower draw—and saves fuel—when the hydraulic system is not being used. The dry valve, in its closed position, allows only enough oil to pass to maintain pump lubrication. This lube oil, about 1½ GPM, is returned to reservoir via a bleed valve and small return line. A fully functioning bleed valve is crucial to the life of the dry valve pump. Cavitation induced pump failure will result if a bleed valve becomes clogged with contaminates. Muncie Power also manufactures a butterfly-style dry valve, called a Powr-Pro valve, which eliminates the bleed valve requirement and provides for improved system efficiency.

*Note: The wear plates and shaft seals for a dry valve-type pump differ from the standard gear pump parts. Attempting to fit a dry valve to a standard gear pump will likely result in premature pump failure.*

**Live Pak™ pumps**
Like dry valve pumps, Live Pak™ pumps are used primarily on refuse vehicle applications. Unlike dry valve pumps, Live Pak™ pumps do not have their inlet fitted with a shut-off valve. Instead, their outlets incorporate a flow limiting valve, called a Live Pak™ valve, which acts as an unloading valve in the OFF position and a flow limiting valve in the ON position. This has the effect of limiting the hydraulic system speed to keep it within safe operating parameters. These pumps also are typically engine crankshaft driven.
SECTION 4: DIRECTIONAL VALVES

Hydraulic circuits, construction types, and sectional
As their name implies, directional control valves direct the oil flow produced by the pump to the various actuators (cylinders and motors) of the system and or back to tank. As previously discussed, there are two types of hydraulic circuits, open center and closed center. These circuits require very different directional valves. Open center valves, found on dump trucks, refuse vehicles, wreckers and most other truck-mounted applications, have a passage called the open center passage, or open center core, to a return port which directs unused oil flow back to tank. Open center valves are used in systems with fixed displacement pumps. Closed center valves, frequently found in central hydraulic systems for snow and ice control vehicles and some utility equipment, are used with variable displacement piston pumps and do not have this open center passage.

Directional valves can be of two construction types, monoblock and sectional. The monoblock valve is one which has been machined from a single casting and contains the valve’s inlet, work, and return porting in a single block. The sectional, or stack, valve is more versatile, having separate inlet, work, and return sections that can be configured to suit any application. Sectional valves are popular with hydraulic component distributors because of their versatility and serviceability.

Spool positions and flow paths
Besides being discussed in terms of open or closed center, valves are also described in terms of their spool positions and flow paths, e.g.; three-position, four-way. In this example three-position refers to the raise, neutral and lower positions of the valve spool. four-way refers to the internal flow paths of the work section: (1) in from supply, (2) pressure to extend, (3) pressure to retract, and (4) return to tank. Valves with two spool positions are typically selector valves used to direct oil flow to either of two hydraulic circuits. The directional valve we are most accustomed to in mobile hydraulics is the three-position—raise, neutral, and lower—type.

Three-way valve sections are used to control single acting, “power up, gravity down” hydraulic cylinders. Four-way sections control double acting, “power up, power down” cylinders. A special type of four-way valve section, called a free flow or motor section, is used to supply oil flow to a hydraulic motor. This section differs from the standard four-way section in that the spool is machined to allow crossover flow between the work ports and the “return core” of the valve while in the neutral position. This prevents movement of the driven component from damaging the motor.

Flow and relief cartridges
Directional control valves are specified according to the volume of oil flow they must carry, operating pressure and number, and type of work sections required. Valve manufacturers specify nominal and maximum flow rates as well as maximum operating pressures. The nominal flow is the flow rate at which the valve reaches peak efficiency. When exceeding maximum flow and pressure, excess heat generation will occur.

All valves have an inlet section, which receives flow from the pump and often is equipped with a system pressure relief cartridge, one or more work sections to direct flow to the actuators (cylinders and motors), and a return section to direct oil back to the reservoir. The work sections are specified according to the function of the actuator: single acting, double acting, or motor. In addition, the work sections can be equipped with one or more options such as individual port relief cartridges, flow restrictors, or anti-cavitation valves.

Individual port relief cartridges allow for some work ports or valve sections to have different pressure relief settings than the other system functions. This option is commonly specified for the down stroke of a double-acting dump body cylinder. Flow restrictors are used to limit flow and thereby actuator speeds.
Anti-cavitation valves will prevent cylinder cavitation in double acting cylinders caused by excessive speed in the down stroke. Another option is the power beyond a.k.a. high pressure carryover (HPCO), used to route pressurized oil downstream to another valve.

Each work section in a directional control valve also has multiple spool action or “back cap” options. These include: spring centering, three-position detent, four-position detent, magnetic release, and so on.

Directional control valves can be shifted with short handled levers, cable controls, lever linkage, direct- or pilot-operated solenoid controls, hydraulic controls, or pneumatic controls. These all tend to be customer preference options but are largely influenced by valve location and climate.

SECTION 5: OTHER VALVES

Other valves used in mobile hydraulic circuits include flow dividers, selector valves and in-line relief valves.

Flow dividers are used to split the flow produced by a single pump so that two systems can operate simultaneously. Flow dividers can be either proportional or adjustable. Proportional flow dividers will split the incoming flow, regardless of flow rate, on a proportional basis (50/50, 75/25, etc.). Adjustable flow dividers, sometimes called priority flow dividers, by means of an adjustable, pressure compensated orifice, set the flow to the primary, or controlled, outlet, with the balance of the flow directed to the excess flow outlet. This type is commonly used to limit the speed of a hydraulic motor or cylinder by allowing no more than a set volume of oil flow to reach it.

Selector valves are used to direct all oil flow to one circuit or another, rather than splitting it into two paths. The basic selector valve is a two-position, three-way valve. This valve is frequently used on dump trucks that pull a separate, “pup” trailer.

In-line relief valves, as the name implies, are auxiliary relief valves that can be mounted anywhere on the pressure side of the circuit. They can be used to isolate a part of the system, to provide pressure protection to individual components, or to supplement the main system relief.

Relief valves can be of either the direct acting or pilot operated type. In a direct acting relief, the system pressure pushes against a spring loaded plunger. When system pressure exceeds spring tension the valve opens and pressure is relived to reservoir. Pilot operated relief valves utilize system pressure along with spring tension to create a smoother acting, more accurate valve.

Typically relief valves should be set approximately 15% above the equipment manufacturer’s recommended operating pressure. Setting the relief pressure too close to operating pressure can result in premature and unnecessary relief valve functioning. In turn, this can create noise and heat problems as well as erratic operation. Remember, oil passing over the small orifice of a relief valve is a common cause of system overheating. This occurs when a valve is improperly adjusted or is sticking due to trapped contaminates.

The relief line going back to tank must be of sufficient diameter to carry the flow. If the relief valve or line is too small, it is possible to force flow into the system by saturating the relief valve. This condition can easily result in system damage.

Always check relief valve settings when replacing a pump as it is common practice for inexperienced mechanics to attempt to correct for lost pump efficiency by “turning up the pressure.”

The relief valve should never be adjusted unless there is a pressure gauge installed to determine the proper setting.
SECTION 6: ACTUATORS

The actuators are the hydraulic components that actually perform the physical work in the system. They are the components that convert fluid power into mechanical power. Hydraulic cylinders and motors are the system actuators.

Hydraulic cylinders convert fluid power into linear motion to raise a dump body or angle a plow, for example. Hydraulic cylinders may be single- or double-acting, or single-stage (rod cylinders) or multiple-stage (telescopic cylinders).

Single-acting cylinders, also referred to as “power up/gravity down” type, are extended by supplying flow to the base of the cylinder, pushing the cylinder’s piston, and extending the rod. The single-acting cylinder relies on an opposing force, weight, and gravity, to retract. This type of cylinder is commonly found on dump bodies and snow plow lifts. Most telescopic cylinders are single-acting.

Double-acting, or “power up/power down,” cylinders are hydraulically powered in both directions. Double-acting cylinders are used where the cylinder will be mounted in a horizontal position or where greater control of the return stroke is desired. Snow plow angling and crane arms are common truck-mounted applications. While most double-acting cylinders are single stage, there are applications which require the longer stroke of a telescopic cylinder.

Pressure = Force ÷ Area

The theoretical hydraulic system pressure required to move a hydraulic cylinder can be calculated by dividing the load (weight to be lifted) by the area of the hydraulic cylinder’s piston. Notice that this is the theoretical pressure requirement. In actuality, to begin movement from a standstill, approximately 30% more pressure is required. To accelerate movement, approximately 10% more pressure is required. This added pressure is necessary to overcome friction within the cylinder. Obviously, other factors come into play in determining pressure requirements. Is the load being lifted straight up or pivoted, as in a dump body application? If the load is being moved horizontally, what frictional forces must be overcome? Does the load shift during cylinder travel?

How fast does a hydraulic cylinder extend or retract? If you desire to extend a cylinder in a given amount of time, how much flow will be required of the pump? How does pump efficiency affect cylinder speed? All of these questions can be answered by a simple calculation. Remember your basic high school geometry class and the formula \(\pi r^2\)? You used to calculate the area of a circle. The \(\pi\), or pi symbol, stands for 3.14; \(r\) is the radius (½ the diameter) of a circle; and to square a number \(x^2\) means to multiply it times itself. The formula then is \(r \times r \times 3.14\) to get the area that is referred to in the above formula. This would be the

<table>
<thead>
<tr>
<th>CYLINDER FORCE CAPACITY</th>
<th>FIGURES IN THE BODY OF THE CHART ARE THRUST VALUES IN POUNDS</th>
</tr>
</thead>
<tbody>
<tr>
<td>PISTON OR ROD DIA.</td>
<td>AREA SQ. IN.</td>
</tr>
<tr>
<td>2&quot;</td>
<td>3.14&quot;</td>
</tr>
<tr>
<td>2½&quot;</td>
<td>4.91&quot;</td>
</tr>
<tr>
<td>3&quot;</td>
<td>7.07&quot;</td>
</tr>
<tr>
<td>3½&quot;</td>
<td>9.62&quot;</td>
</tr>
<tr>
<td>4&quot;</td>
<td>12.57&quot;</td>
</tr>
<tr>
<td>5&quot;</td>
<td>19.64&quot;</td>
</tr>
<tr>
<td>6&quot;</td>
<td>28.27&quot;</td>
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<td>7&quot;</td>
<td>38.49&quot;</td>
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<tr>
<td>8&quot;</td>
<td>50.27&quot;</td>
</tr>
<tr>
<td>9&quot;</td>
<td>63.62&quot;</td>
</tr>
<tr>
<td>10&quot;</td>
<td>78.54&quot;</td>
</tr>
</tbody>
</table>
e.g.: 8 GPM is sent to a 6" diameter hydraulic cylinder. How fast will it extend?
The area of the piston is 28.27 sq.in. (πr²)

8 GPM × 231 ÷ 28.27 sq.in. = 65.37" per minute of rod travel

If you don’t see your cylinder in the chart at the right, use the factors below to determine fill and extension requirements.

**HYDRAULIC CYLINDER CAPACITY REQUIREMENTS**

<table>
<thead>
<tr>
<th>DIAMETER OF LARGEST MOVING STAGE</th>
<th>NUMBER OF STAGES</th>
<th>LENGTH OF StROKE</th>
<th>GALLONS REQUIRED TO FILL (APPROX.)</th>
<th>GALLONS REQUIRED TO EXTEND (APPROX.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>5&quot;/3 stage</td>
<td>3</td>
<td>84</td>
<td>2.1</td>
<td>4.7</td>
</tr>
<tr>
<td>6&quot;/3 stage</td>
<td>3</td>
<td>84</td>
<td>3.0</td>
<td>7.3</td>
</tr>
<tr>
<td>6&quot;/4 stage</td>
<td>4</td>
<td>108</td>
<td>3.9</td>
<td>9.4</td>
</tr>
<tr>
<td>7&quot;/3 stage</td>
<td>3</td>
<td>120</td>
<td>4.3</td>
<td>10.4</td>
</tr>
<tr>
<td>7&quot;/4 stage</td>
<td>4</td>
<td>130</td>
<td>6.5</td>
<td>16.3</td>
</tr>
<tr>
<td>8&quot;/4 stage</td>
<td>4</td>
<td>135</td>
<td>4.8</td>
<td>14.3</td>
</tr>
<tr>
<td>8&quot;/5 stage</td>
<td>5</td>
<td>156</td>
<td>5.5</td>
<td>16.6</td>
</tr>
<tr>
<td>9&quot;/5 stage</td>
<td>5</td>
<td>160</td>
<td>6.3</td>
<td>24.3</td>
</tr>
<tr>
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<td>5</td>
<td>170</td>
<td>5.6</td>
<td>21.8</td>
</tr>
<tr>
<td>8&quot;/5 stage</td>
<td>5</td>
<td>190</td>
<td>6.3</td>
<td>24.3</td>
</tr>
<tr>
<td>8&quot;/5 stage</td>
<td>5</td>
<td>220</td>
<td>7.3</td>
<td>28.2</td>
</tr>
<tr>
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<td>5</td>
<td>235</td>
<td>7.8</td>
<td>30.1</td>
</tr>
<tr>
<td>8&quot;/5 stage</td>
<td>5</td>
<td>250</td>
<td>8.3</td>
<td>32.0</td>
</tr>
<tr>
<td>8&quot;/5 stage</td>
<td>5</td>
<td>265</td>
<td>8.8</td>
<td>33.9</td>
</tr>
<tr>
<td>9&quot;/5 stage</td>
<td>5</td>
<td>220</td>
<td>10.1</td>
<td>38.3</td>
</tr>
<tr>
<td>9&quot;/5 stage</td>
<td>5</td>
<td>235</td>
<td>10.8</td>
<td>40.9</td>
</tr>
<tr>
<td>9&quot;/5 stage</td>
<td>5</td>
<td>250</td>
<td>11.5</td>
<td>43.5</td>
</tr>
<tr>
<td>9&quot;/5 stage</td>
<td>5</td>
<td>285</td>
<td>12.8</td>
<td>47.9</td>
</tr>
</tbody>
</table>
how many gallons are required to fill the empty cylinder before it begins to move. This will only apply the first time the cylinder is extended, thereafter these areas will contain oil. The extend capacity represents the volume of oil required to fully extend the cylinder. This information is also available from the hydraulic cylinder manufacturer or distributor.

**Cylinder maintenance and troubleshooting**
When first installed, hydraulic cylinders must be bled to remove air. Air trapped in a cylinder will cause the cylinder to move in a jerky manner as air, under pressure, will compress. The compression of air in a hydraulic system also creates heat. Cylinders are equipped with a bleed screw to facilitate the removal of air. Air can get into a cylinder and oil can leak out, if the packing seals become damaged, or if the rod becomes rust pitted, or scored by contaminates.

Watch a telescopic cylinder extend and retract. Extension should always begin with the largest diameter section and progress to the smallest. If it does not, there is a problem with the cylinder, not the pump. Retraction should be just the opposite: smallest section first, largest last.

Cylinders that have to control heavy loads are sometimes equipped with a counterbalance valve to prevent the cylinder from bleeding down or retracting too rapidly, creating a dangerous operating condition. The counterbalance valve is typically nonadjustable to prevent tampering and allows for greater operator control of the loaded cylinder.

Cylinders should be stored in a vertical position to prevent seal distortion and with their ports plugged to keep contaminates out.

**Hydraulic motors**
These motors are commonly referred to as “torque motors,” convert fluid energy into rotary mechanical energy—just the opposite of a hydraulic pump. In fact, if equipped with the proper shaft seal and a case drain port, a pump can sometimes be used as a hydraulic motor.

Motors are broadly classified as either high-speed/low-torque motors, or low-speed/high-torque motors. The latter, also called a gerotor motor, is the type we are probably most accustomed to. This is the type that is commonly used for hydraulic winch drives, turrets for cranes or aerial ladders, or auger drives. These motors typically operate at speeds ranging from less than 100 RPM upward to 800 RPM. The gerotor design has the advantage of multiplying torque within the motor, making it an excellent choice for applications requiring high start-up torque. This is also the type used for wheel drives.

High-speed/low-torque motors will operate at speeds ranging from 800 to 3,000 RPM. Gear pumps are often used as high-speed motors. When used in this fashion the outlet, or high pressure port, becomes the inlet and visa versa. A case drain port, plumbed to reservoir, relieves pressure behind the shaft seal.

Hydraulic motors, by their nature, are inefficient and can generate a great deal of heat—particularly if the duty cycle is long. These applications often require the use of oil coolers to keep operating temperatures at acceptable levels. To properly select a hydraulic motor it is necessary to know the speed at which the motor shaft must turn and the horsepower it must deliver.
SECTION 7: RESERVOIRS

Reservoirs serve three purposes in the hydraulic system: (1) they store the oil until the system requires it, (2) they help provide for the cooling of the oil, and (3) they provide a place for contaminants to “settle out” of the oil. Material, volume, location, and shape are important considerations in selecting a hydraulic reservoir.

Oil reservoirs can be constructed from steel, aluminum, or polyethylene plastic. Each of these materials has benefits and drawbacks which should be considered when selecting a reservoir.

Steel can dissipate moderate amounts of heat and are relatively easy to construct. Steel plate is readily available and inexpensive. However, steel reservoirs are susceptible to moisture condensation and rust. Also, it is not uncommon to find welding slag and splatter, which can damage system components, inside steel reservoirs. Steel is also heavy.

Aluminum is both an attractive material and has good heat dissipation, providing three times the heat transfer rate of steel. It is the choice of owner operators who equip their trucks with custom paint jobs and every imaginable option. But aluminum is expensive and requires a higher level of skill on the part of the fabricator. It is common for fabricators to split a 100 gallon fuel tank using half for fuel and half for hydraulic fluid. This situation presents numerous potential problems: the fluids must remain isolated, diesel fuel can be mistakenly added to the hydraulic oil, and there is often no design provision (diffuser) to help manage high volume return flow as in the case of a dump trailer. Also, condensation can cause aluminum to oxidize.

Polyethylene (poly) plastic reservoirs are light in weight and can be molded in various shapes and even colors. The manufacturing process does not generate contamination particles and polyethylene is less susceptible to moisture condensation. However, polyethylene is not a good dissipater of heat and should not be used for long duty cycle applications like hydraulic motor drives or live floors. Use it instead for dump, roll-off, or ejector type applications which have short duty cycles.

Size and placement

How large does a reservoir need to be to ensure an adequate supply of oil? There are two rules of thumb that can be used as a starting point. If the hydraulic system uses cylinders as its actuators, the reservoir capacity should equal the volume of oil required to extend the cylinders plus 20% (or 4-6 inches) reserve in the tank. If the system utilizes hydraulic motors as actuators, the reservoir capacity should equal to twice the operating system flow rate. These rules are not absolute; they are affected by such factors as ambient temperature, length of duty cycle, frequency of use, etc. Remember, the goal is to keep an adequate supply of oil and to keep it cool.

Placement of the reservoir is important. The primary job of the reservoir is to provide oil to the pump. Therefore, the ideal location is close to and directly above the pump’s inlet port. While possible in an industrial setting, this is often impossible to achieve in a truck-mounted system. When the pump is mounted on the front of the vehicle or on top of the engine, the reservoir outlet is likely to be several feet away and below the pump inlet. In these conditions, it is important that the inlet hose be oversized and kept as straight as possible to prevent cavitation of the pump. In some cases, it may be necessary to use a sealed, pressurized reservoir.
Construction considerations
The reservoir must be able to breathe, to take in, and exhaust air as the fluid level changes. Therefore, it is important that the reservoir be equipped with a vent or breather cap. An improperly vented reservoir can starve the pump, so clean the breather frequently.

The reservoir should be constructed so that returning oil flow always enters the tank below the oil level, either by placing the return port at the bottom or by directing the oil through a stand pipe to the bottom. Oil entering above the fluid level may create foam and air bubbles (aeration), which can then enter the system resulting in sluggish or jerky operation. A diffuser will further dissipate oil flow below the fluid level. Diffusers effectively manage high volume return flows common with dump applications.

Another important design consideration is tank port placement and size. The pump inlet and return ports should be on opposite ends of the reservoir to allow the returning oil to lose heat before again being introduced back into the system. To further keep the warmer, returning oil away from the pump inlet port and to help prevent sloshing, tanks may be equipped with baffles. Baffles should be located to direct the returning oil toward the walls of the reservoir where heat can be transferred to the atmosphere. The oil should take the longest possible route to the tank’s outlet port. To keep settled contaminates from entering the system, the tank outlet port should be raised slightly from the reservoir bottom.

Low profile tanks may be attractive from the standpoint of ground clearance but can expose the pump inlet to atmosphere when operating off-road or on an incline. In addition, an inlet line vacuum may create a vortex and draw air into the system.

Temperature and fluid level gauges, fill screens, clean-out ports, and magnetic drain plugs are useful options for hydraulic oil reservoirs.

To improve inlet conditions in piston pump systems pressurized reservoirs are frequently used; 3-4 PSI is normal for these applications.

Calculating reservoir capacity is a matter of simple geometry. For square or rectangular tanks multiply the length (in inches) by the height, by the width. This will yield the volume in cubic inches. Convert it to gallons by dividing by 231.

For cylindrical reservoirs, we use the same formula that we used to determine the fill volume of a hydraulic cylinder: \(\pi r^2 \times \text{length} \div 231 = \text{gal.}\)

**Note:** The above example does not consider the reservoir wall thickness, which will take away slightly from the actual capacity; along with the air gap; baffles or support structure; port size and location; or minimum oil level above the port to prevent uncovering or a vortex affect. Subsequently, the usable capacity of a reservoir is considered to be 80% of its total calculated volume.
SECTION 8: OIL FILTERS

It has been estimated that between 70% and 90% of hydraulic system failures are the result of contamination. Filters, properly selected and maintained, will prevent contaminants from damaging hydraulic components and enable the system to run cooler, quieter, and longer. Filters may be located in the pump's inlet, pressure, or return line.

Suction strainers are located inside the reservoir and are useful in catching large objects like welding slag, shop rags, bolts, hand tools, and rocks. The typical strainer consists of a 100 mesh screen.

Suction filters, located between the reservoir and pump, offer the attractive benefit of filtering the oil before it reaches the pump. A good theory that may not work out so well in practice if the filter element is not properly selected and changed regularly. Remember, it is important that the pump inlet not be restricted and anything, including a filter, on the inlet side adds to the restriction the oil must get through to get to the pump. Some piston pump applications may require a 3 micron suction filter and either a charge pump or pressurized breather cap. The rule of thumb for sizing a suction filter size is four times system flow.

Pressure filters are located on the outlet (pressure) side of the pump and prevent wear generated contaminate particles from entering valves, cylinders, and motors. The addition of pressure accelerates the damage that contaminates cause. Pressure filters are expensive, however, in mobile applications they are mainly found in closed center, piston pump systems.

Return filters are the most common type found in truck-mounted hydraulic systems. Return filters are readily available, inexpensive, and easy to service. Replacement canister elements are often interchangeable between manufacturers. The most common is a 10 micron, spin-on type. The rule of thumb for filter size is to specify the filter for two times system flow.

Filter carts, sometimes referred to as off line filters, are useful for removing contaminates from new oil (“new” does not always mean “clean”) and as part of a preventative maintenance program to prevent contamination damage. These filter systems remove the oil from the system, run it through filters, and put it back clean and ready to go. This process is sometimes referred to as kidney loop filtration.
SECTION 9:
HOSE AND FITTINGS

Hydraulic hoses must be the proper size and type to carry the oil at the specified rate of flow and pressure. Undersized hoses create unnecessary restriction, contributing to excessive neutral system pressures and added heat. Using the wrong hose for an application can result in leakage or bursting under pressure or, on the inlet side of the pump, to cavitation.

The Society of Automotive Engineers (SAE) has designations for hydraulic hose based on their intended usage and the fluid to be carried. The designations we are most concerned about for truck-mounted hydraulic systems are SAE 100R4, 100R1, 100R2 and 100R17, 1SC, and 2SC. These designations can be found printed at regular intervals on the lay line of the hose. Also, hoses have maximum recommended oil velocity ratings based on their location in the system. Oil velocity is expressed in feet per second (FPS); it should not exceed the following: inlet hose at 4 FPS, return hose at 8 FPS, and pressure hose at 15 FPS.

Velocity (V) can be calculated by the formula: \( V = \text{GPM} \times 0.3208 \div \text{A} \); where GPM is the flow rate and area (A) is the inside area of the hose.

SAE 100R4 is suitable for the inlet side of the hydraulic pump. This type of hose has an inner tube securely bonded to a spiral wire wrap covered by a reinforcing layer. This prevents the hose from collapsing under the vacuum found in an inlet condition, something that more expensive pressure hose is prone to do.

SAE 100R1/1SC hose contains a single wrap of braided wire and is suitable for low pressure return hoses. This hose can collapse under a vacuum condition and should not be used on the inlet side of the pump. This type of hose is often referred to as single wire hose.

SAE 100R2/2SC; SAE 100R17 hose that is also known as two-wire hose, has two layers of wire wrap and is capable of handling higher system pressures. Use it between pumps and valves and between valves and actuators.

SAE 100R7/100R8 hose is a specially constructed, non-conductive, hose often used in aerial bucket applications for obvious safety reasons. It is easily recognized by its bright orange color.

SAE 100R13; SAE 100R15; 4SH rated hose is also a high pressure hose having multiple wire spiral layers.

The pressure rating for a particular hose is dependent on both the SAE type and the size of the hose. You may note in the chart shown that as the hose diameter increases the pressure rating decreases. Hoses have two pressure ratings, working and burst, with a safety factor of 4:1. That is, a hose with an 8,000 PSI burst pressure will have a 2,000 PSI working pressure.

### HOSE WORKING PRESSURES

<table>
<thead>
<tr>
<th>HOSE SIZE</th>
<th>¼ (-04)</th>
<th>3/8 (-06)</th>
<th>½ (-08)</th>
<th>5/8 (-10)</th>
<th>¾ (-12)</th>
<th>1 (-16)</th>
<th>1¼ (20)</th>
<th>1½ (-24)</th>
<th>2 (-32)</th>
</tr>
</thead>
<tbody>
<tr>
<td>HOSE TYPE</td>
<td>MAXIMUM WORKING PRESSURE*</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>SAE 100R1</td>
<td>2,800</td>
<td>2,250</td>
<td>2,000</td>
<td>1,500</td>
<td>1,250</td>
<td>1,000</td>
<td>625</td>
<td>500</td>
<td>375</td>
</tr>
<tr>
<td>1SC</td>
<td>3,200</td>
<td>2,600</td>
<td>2,300</td>
<td>1,800</td>
<td>1,500</td>
<td>1,250</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>SAE 100R17</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
<td>3,000</td>
</tr>
<tr>
<td>SAE 100R2</td>
<td>5,000</td>
<td>4,000</td>
<td>3,500</td>
<td>2,800</td>
<td>2,250</td>
<td>2,000</td>
<td>1,625</td>
<td>1,250</td>
<td>1,125</td>
</tr>
<tr>
<td>2SC</td>
<td>5,800</td>
<td>4,800</td>
<td>4,000</td>
<td>3,600</td>
<td>3,100</td>
<td>2,400</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>SAE 100R4</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>300</td>
<td>300</td>
<td>250</td>
<td>20</td>
<td>150</td>
<td>100</td>
</tr>
<tr>
<td>SAE 100R7</td>
<td>3,000</td>
<td>2,300</td>
<td>2,000</td>
<td>1,500</td>
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<td>–</td>
<td>–</td>
<td>–</td>
</tr>
</tbody>
</table>

* Note: Minimum burst pressure is four times maximum working pressure.
Hose sizes are based on a dash size system wherein -16 is equal to 1 inch. Thus, an SAE 100R1 -16 is a low pressure return hose with an inside diameter of 1 inch. An SAE 100R4 -24 is an inlet hose with an inside diameter of 1½ inches and an SAE 100R2 -12 is a high pressure hose with an inside diameter of ¾ inch.

**Hose routing tips:**
- Do not exceed the manufacturer's recommended minimum bend radius of the hose.
- Do not allow a hose to be twisted. Mounting a hose with a 10 degree twist can shorten the life of the hose by as much as 90%.
- Never allow the outside bend of a hose to face the machine operator.
- Route hose so that it flexes in only one plane. The printed “lay line” of the hose should stay in one plane.

For long runs, tubing or piping is often used. Besides being an economical method, metal tubing has the added benefit of improved heat dissipation. Always confirm that the chosen tubing is capable of withstanding the system operating pressures. Galvanized or black pipe is not recommended for several reasons, pressure being one. At a standard safety margin of 4:1, 1 inch diameter schedule 40 pipe has a working pressure rating of only 1,450 PSI and schedule 80 a rating of 2,500 PSI, marginal at best. Also, the galvanized coating can flake and create contaminants. Finally, the inside of the pipe is rough, adding to fluid turbulence, pressure drop, and heat generation.

**Remember:** Hose is measured on the inside diameter, tubing and pipe on the outside.

Pipe thread fittings (NPT) are common, primarily due to cost and availability. However, they are probably the worst choice for a hydraulic system. In order to make them seal, installers will routinely use Teflon tape, pieces of which can clog small passages and cause valves to malfunction. There are also dangers in overtightening NPT fittings, particularly if Teflon tape is used, and damaging both pump and valve castings. A better choice would be the O-Ring face seal fittings SAE 37° Joint Industry Council (JIC) flare fittings or the straight thread, O-Ring type Unified National Thread (UNF). These allow for better positioning of hoses and will seal without the use of tape or liquid thread sealant. Another advantage of these fittings is that they are reusable. Pipe thread fittings, which only seal as threads are deformed, should never be re-used.

**Bending Radius:**

The bend radius of hose is measured to the outer wall of the inside of the bend. The bend radius of tubing is measured to the center of the tube.
**Fitting Installation Torques**

### FITTING TORQUE VALUES FOR NPT (PIPE) FITTINGS

<table>
<thead>
<tr>
<th>THREAD SIZE</th>
<th>ASSEMBLY TURNS</th>
</tr>
</thead>
<tbody>
<tr>
<td>¼</td>
<td>2 – 3</td>
</tr>
<tr>
<td>⅜</td>
<td>2 – 3</td>
</tr>
<tr>
<td>½</td>
<td>2 – 3</td>
</tr>
<tr>
<td>⅜</td>
<td>⅜ – ⅞</td>
</tr>
<tr>
<td>¾</td>
<td>⅞ – 1⅔</td>
</tr>
<tr>
<td>1¼</td>
<td>1⅔ – 2¾</td>
</tr>
<tr>
<td>1½</td>
<td>1⅔ – 2¾</td>
</tr>
</tbody>
</table>

Tighten the fitting finger tight, mark with a line, then tighten the indicated number of turns. PASTE ONLY, DO NOT USE TEFLON TAPE.

### FITTING TORQUE VALUES FOR JIC 37° FLARE FITTINGS

<table>
<thead>
<tr>
<th>LINE SIZE</th>
<th>ROTATE NO. OF FLATS</th>
</tr>
</thead>
<tbody>
<tr>
<td>-04</td>
<td>1½ – 1¾</td>
</tr>
<tr>
<td>-05</td>
<td>1 – 1⅔</td>
</tr>
<tr>
<td>-06</td>
<td>1 – 1⅔</td>
</tr>
<tr>
<td>-08</td>
<td>1⅔ – 1¾</td>
</tr>
<tr>
<td>-10</td>
<td>1⅔ – 1¾</td>
</tr>
<tr>
<td>-12</td>
<td>1 – 1½</td>
</tr>
<tr>
<td>-16</td>
<td>¾ – 1</td>
</tr>
<tr>
<td>-20</td>
<td>½ – ¾</td>
</tr>
<tr>
<td>-24</td>
<td>½ – ¾</td>
</tr>
<tr>
<td>-32</td>
<td>¼</td>
</tr>
</tbody>
</table>

Tighten the fitting finger tight, mark with a line, then tighten the indicated number of flats.

### FITTING TORQUE VALUES FOR STRAIGHT THREAD UNF FITTINGS

<table>
<thead>
<tr>
<th>TUBE O.D.</th>
<th>LINE SIZE</th>
<th>TORQUE (ft.lb.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>.25</td>
<td>-04</td>
<td>8 – 10</td>
</tr>
<tr>
<td>.312</td>
<td>-05</td>
<td>10 – 14</td>
</tr>
<tr>
<td>.375</td>
<td>-06</td>
<td>17 – 21</td>
</tr>
<tr>
<td>.50</td>
<td>-08</td>
<td>31 – 39</td>
</tr>
<tr>
<td>.625</td>
<td>-10</td>
<td>51 – 59</td>
</tr>
<tr>
<td>.75</td>
<td>-12</td>
<td>71 – 79</td>
</tr>
<tr>
<td>1</td>
<td>-16</td>
<td>93 – 107</td>
</tr>
<tr>
<td>1.25</td>
<td>-20</td>
<td>127 – 140</td>
</tr>
<tr>
<td>1.50</td>
<td>-24</td>
<td>160 – 173</td>
</tr>
<tr>
<td>2</td>
<td>-32</td>
<td>223 – 243</td>
</tr>
</tbody>
</table>

### FITTING TORQUE VALUES FOR SAE FLANGE FITTINGS

**CODE 61**

<table>
<thead>
<tr>
<th>CONNECTOR SIZE</th>
<th>MAXIMUM WORKING PRESSURE (PSI)</th>
<th>TORQUE (ft.lb.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>-08</td>
<td>5,000</td>
<td>15 – 19</td>
</tr>
<tr>
<td>-12</td>
<td>5,000</td>
<td>21 – 29</td>
</tr>
<tr>
<td>-16</td>
<td>5,000</td>
<td>27 – 35</td>
</tr>
<tr>
<td>-20</td>
<td>4,000</td>
<td>35 – 46</td>
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<tr>
<td>-24</td>
<td>3,000</td>
<td>46 – 58</td>
</tr>
<tr>
<td>-32</td>
<td>3,000</td>
<td>54 – 67</td>
</tr>
</tbody>
</table>

**CODE 62**

<table>
<thead>
<tr>
<th>CONNECTOR SIZE</th>
<th>MAXIMUM WORKING PRESSURE (PSI)</th>
<th>TORQUE (ft.lb.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>-08</td>
<td>6,000</td>
<td>15 – 19</td>
</tr>
<tr>
<td>-12</td>
<td>6,000</td>
<td>5 – 33</td>
</tr>
<tr>
<td>-16</td>
<td>6,000</td>
<td>42 – 50</td>
</tr>
<tr>
<td>-20</td>
<td>6,000</td>
<td>63 – 75</td>
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<tr>
<td>-24</td>
<td>6,000</td>
<td>117 – 133</td>
</tr>
<tr>
<td>-32</td>
<td>6,000</td>
<td>200 – 217</td>
</tr>
</tbody>
</table>
**HYDRAULIC FLUID RECOMMENDATIONS FOR GEAR PUMPS**

Max. Intermittent......7,500 SSU (1620 cSt)
Max. Continuous........1,000 SSU (216 cSt)
Min. Continuous...............60 SSU (10 cSt)
Max. Temperature Production Seals
Intermittent.........................225° F
Continuous.......................180° F

cSt: Centistokes

**OIL TEMPERATURE**: Pumps and components such as bearings and oil seals will be affected by high heat. Cool operating temperatures (below 130° F) will produce conditions which result in extended oil life, providing target SSU is met.

SSU: Saybolt Seconds Universal
The number of seconds required for 60ml of a fluid to pass through an orifice of a given size at one atmosphere at a controlled temperature. If no temperature is stated, it is assumed as 100° F [38° C.]

Viscosity Index (V.I.) is an indication of a fluid’s rate of change.

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**SYSTEM TEMPERATURE** is the result of many factors, including:

- Overall system efficiency
- Reservoir size and location
- Proximity of components to heat sources
- Duty cycle
- Level of contamination
- Quality of oil
- Ambient temperature

**To lower operating temperatures**:

- Review component selection for undersized components.
- Increase reservoir capacity.
- Shield components and hoses from exhaust systems.
- Keep oil clean.
- Install an oil cooler.

---

**SECTION 10: HYDRAULIC OILS**

Oil must serve several functions within the hydraulic system—deliver power, lubricate components, dissipate heat, and carry away contaminates. To perform these functions, hydraulic oils contain specific additives to enhance their ability to stand up under the pressure, temperature extremes, and other operating conditions to which they are subjected. To a large extent, the life of the hydraulic system is directly tied to the life of the oil. If oil is kept clean and below 140° F the entire system benefits.

**Viscosity** is the measure of how a fluid resists flowing. Oil viscosity is measured in Saybolt Seconds Universal (SSU). This is sometimes also referred to as SUS. This number represents the amount of time it takes 60 milliliters (about 2 ounces) of fluid at a given temperature (usually 100° F) to flow through an orifice of a given size (.060 inch). Oil has a higher viscosity at low temperatures, a lower viscosity at high temperatures. For hydraulic oils, viscosity at startup (cold) should not exceed 7,500 SSU. Viscosity at 100° F should be in the 75–200 SSU range. When you look at the specifications for oil, unless otherwise stated, the SSU specified is at 100° F.

Do not attempt to thin oil with kerosene or diesel fuel for winter operation. Instead switch to a lower viscosity oil or add an approved thinning agent designed for that purpose.

**Lubricity** refers to the ability of oil to maintain a protective film on metal surfaces. Without this oil film, metal to metal contact would create friction, resulting in excessive wear and heat generation. Film thickness is related to viscosity. High viscosity fluids are thicker, forming a thicker film on internal components. Although automatic transmission fluid (ATF) is frequently used as hydraulic fluid, it is actually a poor choice because it loses film strength at high pressures and temperatures. On the positive side, ATF has excellent thermal stability.

In truth, there is much more to oil than petroleum. Oils contain additive packages specific to their function. Motor oil, for example, contains high temperature and detergent additives. Quality hydraulic oils must contain high pressure, anti-rust, anti-wear, and anti-foaming agents. All are necessary for the oil to do its job. Base hydraulic oil selection on frequency of use, maximum PSI, climate, and how essential the piece of equipment is.

It is important to remember that these additives are heat sensitive. The ideal operating temperature for hydraulic systems is 100°–140° F. Temperatures over 180° F can contribute to oxidation, robbing the oil of its ability to perform. As additives cook out they leave behind varnishes, which can cause valves to stick and degrade performance. These oils feel sticky to the touch rather than slick. Heat also affects performance efficiency. As a rule, system efficiency suffers approximately 1% for each 10° F over 130° F. At 180° F, that represents a 5% efficiency loss and a ⅔ reduction in the projected useful life of the oil.

One important function of the hydraulic oil is to deliver contaminates to the filter where they can be removed from the system or to the reservoir where they can settle out rather than be held in suspension.

The number one enemy of hydraulic systems is contamination. We use the word “contamination” rather than “dirt” because contamination can take many forms. There is particulate contamination; chemical contamination; and biological, or microbial, contamination. The latter occurs when there is water present in the system in which biological agents can grow.

**Chemical contamination** includes diesel fuel and kerosene used to thin the oil, water, cleaning chemicals, and liquid calcium chloride. Water is the most common, entering the system through the tank breather as the oil level rises and falls during normal system operation. Pressure washing, if directed toward the reservoir, also introduces water. Oil can absorb up to...
300 parts per million (PPM). Amounts above 300 PPM exist as free water, giving the oil a milky appearance. This is referred to as emulsified water. It has been estimated that as little as 1% water in hydraulic oil can reduce pump bearing life by as much as 90%. The presence of water also accelerates the breakdown of the additive package and promotes the formation of acidic by-products which lead to corrosive wear. Water is also a major contributor to the process of oxidation, the reaction of oxygen to the carbon and hydrogen elements of hydraulic fluids, which results in the formation of sludge and contributes to corrosion.

**Particulate contamination** includes objects large and small in various concentrations. Examples include silt, sand, welding splatter, rust particles, metal shavings, Teflon tape, fibers from rags, bolts, and hand tools. Some particles are large enough to bring a pump to an immediate and violent stop, breaking gear teeth, and shearing input shafts. Others, especially in high concentration and under pressure, have the effect of sandblasting the internal parts of the hydraulic components. In either case, the end result is increased wear and heat, decreasing system efficiency and component life.

How does contamination enter the system? It may be built-in, induced, ingressed, or internally generated.

**Built-in contamination** occurs during the manufacturing and assembly procedure and includes welding slag and splatter, dust from storage, paint chips, Teflon tape particles, and contaminates from “new” oil.

**Hint:** Store oil drums on their sides and filter new oil as it is put into the reservoir to reduce built-in contamination. Store designated oil handling pans, buckets, and funnels upside down in a dust free cabinet.

**Induced contamination** occurs when a system is opened for service and dirt is allowed in. But also, water from pressure washing.

**Ingressed contamination** is that which is drawn into the system during normal operation, usually via the reservoir breather or through cylinder rod seals.

**Internally (wear) generated contaminates** consist of wear particles from pumps, cylinders, and hydraulic motors; rubber compounds from hoses and seals; and varnishes from the breakdown of oil additives.

In analyzing contamination, two factors are considered: size and concentration. The unit of measure for particle size is the **micron (μ)**. Concentration is measured in the number of particles per milliliter, 1/1000 of a liter. A milliliter of oil is about the size of a sugar cube.

So, how large is a micron? The visibility threshold, the smallest object that can be seen with the naked eye, is approximately 40μ. Table salt is 100μ, a human hair has a diameter of 70μ, and a red blood cell is 7μ. Generally, in mobile hydraulics, we employ a 10μ filter.

Oil sampling analysis is a useful tool for determining both the concentration and composition of contaminates. The report details the type of particles found and the concentration, in parts per milliliter, of 5μ and 15μ size particles. A typical oil analysis report shows the concentration of wear metals (i.e., iron, chromium, and aluminum), contaminate metals (i.e., sodium and potassium), additive metals (i.e., magnesium and calcium), and non-metallic contaminates (i.e., water and fuel). These are shown in parts per milliliter (ml) and a final score is determined for the overall system cleanliness. This score is based on a cleanliness code developed by the International Organization for Standardization (ISO). This system assigns a code based on parts per milliliter and establishes minimum cleanliness levels. An improvement in particle contamination of one ISO cleanliness code can result in a 10% to 30% increase in component life. The ISO recommendation for a typical

---

**HOW LARGE IS A MICRON (μ)?**

<table>
<thead>
<tr>
<th>Particle Size</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>149μ</td>
<td>100 mesh screen</td>
</tr>
<tr>
<td>100μ</td>
<td>table salt</td>
</tr>
<tr>
<td>90μ</td>
<td>smog particle</td>
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<tr>
<td>74μ</td>
<td>200 mesh screen</td>
</tr>
<tr>
<td>70μ</td>
<td>human hair</td>
</tr>
<tr>
<td>60μ</td>
<td>pollen</td>
</tr>
<tr>
<td>50μ</td>
<td>fog particle</td>
</tr>
<tr>
<td>40μ</td>
<td>visibility threshold</td>
</tr>
<tr>
<td>25μ</td>
<td>white blood cell</td>
</tr>
<tr>
<td>10μ</td>
<td>talcum powder</td>
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<tr>
<td>7μ</td>
<td>red blood cell</td>
</tr>
<tr>
<td>2μ</td>
<td>bacteria</td>
</tr>
<tr>
<td>1μ</td>
<td>0.00003937&quot;</td>
</tr>
<tr>
<td>1μ</td>
<td>10⁻⁴ cm (1/10,000 cm)</td>
</tr>
<tr>
<td>CONTAMINANT CONCENTRATION (PARTICLES PER ML)</td>
<td>CODE</td>
</tr>
<tr>
<td>---------------------------------------------</td>
<td>------</td>
</tr>
<tr>
<td>10,000,000</td>
<td>30</td>
</tr>
<tr>
<td>5,000,000</td>
<td>29</td>
</tr>
<tr>
<td>2,500,000</td>
<td>28</td>
</tr>
<tr>
<td>1,300,000</td>
<td>27</td>
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<td>0.8</td>
</tr>
<tr>
<td>0.0025</td>
<td>0.7</td>
</tr>
</tbody>
</table>

Another term used in discussing oil and filtration is **beta ratio**. There are two numbers in the beta rating: the particle size and the particle count. The beta rating of a filter is a numerical representation of the filter’s effectiveness in removing particles of a specific size on the first pass. The beta rating number looks something like this: $\beta_{10} = 20$. In this example, the filter is allowing one in 20 particles of a 10 micron size to pass. There, the filter is 95% efficient. If the efficiency rating were 4 instead of 20 the filter would be only 75% efficient; 1 particle in 4 would pass. If the efficiency rating were 50 the filter would be 98% efficient; 1 particle in 50 would pass.

According to ISO standards, a beta ratio of 75 is considered the absolute rating. Any ratio higher than $\beta x = 75$ cannot be statistically verified.

**THE BETA RATIO**

- $\beta_{X} = 4$ is 75% efficient* (1 in 4)
- $\beta_{X} = 10$ is 90% efficient (1 in 10)
- $\beta_{X} = 20$ is 95% efficient (1 in 20)
- $\beta_{X} = 50$ is 98% efficient (1 in 50)
- $\beta_{X} = 100$ is 99% efficient (1 in 100)

*75% efficient means that one particle in four will escape through the filter on the first pass, etc.

**RECOMMENDED ISO CLEANLINESS CODES**

<table>
<thead>
<tr>
<th>New Hydraulic Fluid</th>
<th>20/18/14</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gear Pumps/Motors</td>
<td>19/17/15</td>
</tr>
<tr>
<td>Piston Pumps/Motors</td>
<td>18/16/14</td>
</tr>
<tr>
<td>Solenoid Control Valves</td>
<td>20/18/15</td>
</tr>
<tr>
<td>Proportional Control Valves</td>
<td>17/15/12</td>
</tr>
<tr>
<td>Servo Valves</td>
<td>16/14/11</td>
</tr>
</tbody>
</table>
SECTION 11:

SYSTEM PROTECTION DEVICES COOLERS, ACCUMULATORS, MISCELLANEOUS

When hydraulic systems are designed, components are specified based on a desired flow rate and operating pressure. When systems are operated at higher flow rates, pressure drops increase, and system components can be damaged from the resulting heat. A **system protection device** prevents this damage by limiting the speed at which the operator can activate and operate the equipment. This is accomplished by sensing engine speed from the truck’s alternator and, at a preset RPM, automatically disengaging the clutch-type PTO, electric clutch, or dry valve, thereby shutting down the hydraulics until engine speed is reduced to a safe level. It cannot be used to control conventional mechanically shifted PTOs. As an alternative, many modern truck engines and transmissions can be programmed through their electronic control modules to provide overspeed protection as well as to establish other operating parameters.

**Coolers** remove excess heat from hydraulic systems by routing return oil through a heat exchanger (radiator) where heat can be transferred to atmosphere. Generally speaking, systems producing an excess of 16,000 British Thermal Unit (BTU)/hr will require a heat exchanger. Cooler size is based on the amount of heat (in BTUs) that must be removed to maintain a desirable operating temperature. In a hydraulic system, heat is generated at a rate of 2,545 BTUs, per horsepower (HP), per hour. If a system produces 10 HP and is 80% efficient, 8 HP is doing work and 2 HP is generating heat. 5,090 BTU/hour of heat is being produced.

Some coolers mount in front of the truck radiator and use the engine’s fan to pull air through their coils. Care must be taken to keep the cooling coils free of dirt, bugs, and debris. Also available are self-contained units which include a small reservoir, cooling coils, and an electric or hydraulic motor driven fan. While more expensive, they are compact and easy to install. Coolers should be placed after return line filters in the system as contaminates can not only clog passages in the cooling coils but also hold heat longer, making the oil harder to cool. **Filter first, then cool.**

Hydraulic tool circuits, hydraulically driven product pumps, and any continuous duty hydraulic system are candidates for coolers. Hydraulic tool circuits will generally require that oil temperatures be kept to no more than 100°F to allow for safe and comfortable handling of the tools.

**Accumulators** act like shock absorbers within the hydraulic system. They may be either spring-loaded or nitrogen gas-loaded, which is the most common, and can be either piston or bladder construction. Accumulators absorb sudden pressure spikes or smooth out a system that produces rapid and frequent pressure pulsations. In mobile equipment, they can be found in hydraulic tool circuits or moving floors. As the name implies, accumulators are also used to store hydraulic pressure, which can be used in emergency situations or with the engine off. Accumulators are also used as storage devices to release high volumes of oil for certain machine operations. Subsequently the system can still be sized for the low volume circuit with the added high flow feature when needed.
SECTION 12: SYSTEM DESIGN

Hydraulic schematic symbols:
Hydraulic circuits are drawn using schematic symbols to represent the various components of the system. These drawings can become quite complex and, while similar, there are different standards. Three organizations who publish standards are the National Fluid Power Association (NFPA), American National Standards Institute (ANSI), and the International Organization for Standardization (ISO).

The examples given here are ANSI standard symbols.

For a more complete directory of these symbols, obtain a copy of the Fluid Power Designers' Lightning Reference Handbook published by Berendsen Fluid Power.

Prime movers:
The prime mover supplies the mechanical power to the hydraulic pump. In mobile hydraulic applications the prime mover is typically the truck engine itself, via a PTO or driveshaft assembly. In industrial hydraulic applications, it is commonly an electric motor.

Rotating shaft
This could be a PTO shaft, front engine driveshaft, or the truck's main driveshaft. There is no established schematic symbol for a PTO.

Electric motor
Seen most often in industrial hydraulic applications.

Hydraulic pumps:
The hydraulic pump supplies the oil flow to the system. Pumps can be of the gear, piston, or vane type. The symbol does not differentiate between the types of pump. It can be modified to show the presence of compensators, reliefs, or multiple sections.

Pump uni-rotational fixed displacement
Has a defined inlet and outlet. Can only run in one direction.

Pump bi-rotational fixed displacement
Properly plumbed, can be turned in either direction.

Pump uni-rotational variable displacement
The diagonal arrow indicates that the pump displacement is adjustable.

Pump uni-rotational variable displacement pressure compensated
Besides being variable displacement, this pump has a pressure compensator, which is used to automatically vary the pump output in order to maintain a specific flow and pressure. The symbol also shows a case drain line to tank.

Tandem pump uni-rotational fixed displacement
Tandem pumps have two flow-producing sections in one main body. They may have either a common inlet (such as the unit above), or individual inlets. There are also triple and quad section pumps.
**Hydraulic motors:**
The exact opposite of a pump, the hydraulic motor converts fluid energy to mechanical energy. Like pumps, motors can be of a gear, vane, or piston design. However, the most common type is the gerotor design. Notice that in the motor symbol the flow arrow points inward, while in the pump it points outward. Otherwise the symbols are the same. As in the case of pumps, the symbol makes no distinction as to type of motor—gear, vane, piston, or gerotor.

- Hydraulic motor
  - uni-rotational
  - fixed displacement
- Hydraulic motor
  - bi-rotational
  - fixed displacement
- Hydraulic motor
  - uni-rotational
  - variable displacement

**Hydraulic oil reservoirs:**
The reservoir supplies the oil to the pump. The basic reservoir pictured below is vented to atmosphere, the most common type. A four-sided box indicates a sealed reservoir. Symbols that resemble dial faces on the side of the reservoir indicate the presence of temperature or oil level indicators.

- Reservoir, basic
- Reservoir, with line above fluid level
  - A line shown above the fluid is typically a return line.
- Reservoir, with line below fluid level
  - A line shown below the fluid level is typically the outlet to the pump. This is sometimes shown exiting the reservoir from the bottom.

**Hydraulic filters:**
Filters can be of the suction, pressure, or return type. The basic symbol is the same.

- Filter

**Hydraulic cylinders:**
Like hydraulic motors they are the actuators of the system, converting fluid energy to mechanical energy. Cylinders also multiply force, making it possible to perform a tremendous amount of work.

- Cylinder, single-acting
  - Single acting cylinders are extended by hydraulic force, but rely on gravity or opposing forces to retract.
- Cylinder, double-acting
  - Double acting cylinders are both extended and retracted by hydraulic forces.

**Directional control valves:**
The directional control valve directs the flow of oil to the chosen actuator—a cylinder or hydraulic motor. Directional valves can be of either an open center or closed center design. Open center valves have a direct passageway from the valve’s inlet port to its return, or tank, port. Closed center valves do not have this internal passage. Generally speaking, open center valves are used with gear or vane pumps, and closed center valves are used with variable displacement piston pumps. There are exceptions.

- Basic valve envelope
  - The basic valve envelope consists of a box representing each of the valve spool positions. This symbol indicates that the valve is a three-position valve. Lines drawn inside the boxes show the oil flow paths for each position.
  - This valve center section identifies the port locations of the valve. P is the inlet from the pump; T is the return to tank; and A and B represent the two work ports. The A port is the one closest to the handle end of the valve spool, the B port is closest to the cap end. On any valve drawing all four will be shown for each spool position. For each position, arrows will indicate the corresponding flow condition.
A multiple section valve is drawn with a broken line surrounding the individual sections and a common inlet for all sections. If there are internal relief or load check valves, they are also shown within the enclosure. Each individual valve section is drawn showing its flow path.

This three-section valve has two double and one single-acting section, an integral load check, and a pressure relief valve. Each section is manually activated and is equipped with a spring return.

**Valve actuators:**
These symbols are used to show how the valve is shifted. In a multiple-section valve, each section has its own actuator shown.

- **Spring**
  Usually used to return the valve spool to the neutral position.

- **Detent**
  The valve spool will stay in whichever position it is placed.

- **Manual actuator**

- **Lever**

- **Solenoid**
Pressure compensated

Pilot pressure (hydraulic)

Solenoid and pilot

Other fluid control valves:
Pressure relief valves, selector valves, load check valves, etc. all have their own symbols.

Pressure relief valve, piloted, non-adjusting

Flow restriction, fixed orifice

Adjustable flow control

Check valve

Flow passes right to left, is blocked left to right.

Hydraulic lines, connections, etc.

MOBILE HYDRAULIC SYSTEM DESIGN TIPS:

1. Start with the requirements of the work to be done. How much weight must be lifted by a cylinder? At what speed must a piece of mechanical equipment—product pump, air compressor, or winch shaft—be turned? The answers to these answers will determine required cylinder sizes and or motor displacements.

2. Knowing cylinder size or motor displacement along with duty cycle times determines hydraulic flow and pressure requirements and, in turn, reservoir, valve, hose, and filter selections.

3. The number of hydraulic functions determines the number and function of directional valve sections, relief valve settings, and valve options.

4. Flow and pressure requirements also determine required pump displacement and pressure capability.

5. With pump displacement and pressure known the system horsepower can be calculated and the prime mover, usually a PTO, can be selected based on desired engine operation speed.

Line or hose

A solid line indicates a hose or tube.

Pilot pressure or case drain line

A dotted line indicates a pilot pressure line. This could be either an external line or an internal passage.

Enclosure

A broken line indicates an enclosure, such as a valve body.
SECTION 13:
HYDRAULIC SYSTEM FAILURES AND TROUBLESHOOTING

Most hydraulic system failures are attributable to four causes:

- Contamination
- Cavitation
- Overpressurization
- Heat

Contamination
As we discussed in Section 10, hydraulic oils can be particulate, chemical, or biological. Contaminates wear on system components, add to system heat, and lodge themselves into small orifices.

Large particle contaminates (metal shavings, sand, etc.) create a condition known as phonographing on the surface of the wear plates in a gear pump. Phonographing is so called because the groves worn into the wear plates resemble those of a phonograph record. These grooves diminish the pump’s efficiency, degrading performance, and adding to system heat.

Fine particle contaminates (those smaller than 5µ) in large concentrations will not bring a pump to a sudden and violent end, however, they will cause a pump to wear out prematurely. In sufficient quantities, fine particles can erode a pathway on the wear plate surface from the pressure to the inlet side and upset the pressure balance of the pump. This condition, called jetting, can result in an immediate loss of pressure capability. They also wear on bearings and journals.

Chemical and biological contaminates affect the oil’s ability to maintain a protective film between moving parts. When the oil film breaks down, the resulting wear and friction create particulate contamination and heat.

Cavitation
This occurs when high vacuum at the pump inlet forms gaseous bubbles in the hydraulic oil. These bubbles, formed in a vacuum, implode (collapse) when they reach the pressure side of the pump. The implosion is violent, releasing a great deal of energy in the form of heat—up to 5,000º F at the point of implosion. This release adds to the system heat and the force of the microjet implosion damages wear plates and pump bodies.

Vaporous cavitation is a phase change (ebullition) from a liquid to a gaseous state caused by pressure levels below the vapor pressure of the liquid. Cavitation is often confused with aeration. While both involve bubbles in the oil there is a critical difference. Aeration occurs when atmospheric air enters the system, usually due to low reservoir levels, a leak on the inlet side of the pump, or damaged cylinder packing. Sometimes aeration results when oil has a short dwell time in the reservoir and air cannot dissipate. Air bubbles make controls feel spongy and actuator functions jerky. Also, as pressure compresses the air on the outlet side of the pump, heat is generated. At a pressure of 2,000 PSI, air bubbles are compressed to \( \frac{1}{135} \) of their original size in less than 10 milliseconds.
Vacuum is measured in inches of mercury (in.Hg.). Vacuum in excess of 5 in.Hg. (gear pumps) at the pump inlet can result in the formation and subsequent collapse of vapor bubbles in the oil. The higher the vacuum the more severe the cavitation damage. High vacuum can be caused by several factors, all of which result in restricting oil flow from the reservoir to the pump. These may include:

- Clogged reservoir breather
- Blocked suction strainer or filter
- Closed shut-off valve
- Undersize inlet hose
- Collapsed or kinked inlet hose
- Long inlet hose run
- Cold oil
- Pump inlet above reservoir oil level

Cavitation is detectable by a distinct sound from the pump. Depending on the severity of the condition the noise ranges from a rattling that sounds like “marbles-in-a-metal-box” to a high pitched whine. The noise is the sound of the vapor bubble implosions. The noise may be more pronounced when the oil is cold and lessen as it warms up.

In order to prevent cavitation damage, the cause of the restriction must be determined and corrected. Piston style pumps are the most sensitive to poor inlet conditions and sometimes require charge pumps or pressurized reservoirs to maintain a positive pressure at the pump inlet.

**Overpressurization**

When operating a pump at a pressure above its design parameters, it can damage input shafts, housings, and wear plates. Cylinder packing and hydraulic hoses can fail. Oil flowing across the small orifice of a relief valve can build heat quickly.

Overpressurization damage can occur when the system’s operating pressure is consistently above the pump’s rated pressure capability or when the system is subjected to pressure spikes, sudden increases caused by changing or binding loads. Even when protected by a relief valve, a pump can be damaged by spike pressures if they occur faster than the relief valve can react. Symptoms of overpressurization include excessive gear housing cut-out, cracked pump bodies, twisted input shaft splines or sheared shafts. Pressure spikes or pump operation above recommended pressure can result in an application exceeding the **Shaft Torque Limitation (STL)** of the pump input shaft. This is of special concern in tandem and triple pump applications because the input shaft must bear the torque of all pump sections. The STL for a pump is calculated by multiplying pump displacement by maximum operating pressure, e.g., 3.5 cu.in. × 3,000 PSI = 10,500 STL.

<table>
<thead>
<tr>
<th>SHAFT SIZE</th>
<th>STL FACTOR</th>
</tr>
</thead>
<tbody>
<tr>
<td>.625” – 9T</td>
<td>≤ 5,490</td>
</tr>
<tr>
<td>.75” – 11T</td>
<td>≤ 10,114</td>
</tr>
<tr>
<td>.875” – Rd</td>
<td>≤ 11,200</td>
</tr>
<tr>
<td>.875” – 13T</td>
<td>≤ 16,500</td>
</tr>
<tr>
<td>1.0” – Rd</td>
<td>≤ 16,900</td>
</tr>
<tr>
<td>1.0” – 15T</td>
<td>≤ 25,650</td>
</tr>
<tr>
<td>1.25” – 14T</td>
<td>≤ 33,300</td>
</tr>
<tr>
<td>1.25” – Rd</td>
<td>≤ 35,900</td>
</tr>
</tbody>
</table>
Heat
In a hydraulic system, heat is frequently the symptom, rather than the cause, of a problem. Heat is often a by-product of cavitation, contamination, and or overpressurization. It can also be caused by undersized valve components, hoses, or reservoirs. A sticking or misadjusted relief valve is a potential heat generator. Hoses or components situated in close proximity to exhaust systems will absorb heat and transfer it to the oil. Excessive heat damages the oil by promoting oxidation, diminishing lubricity, and forming varnish deposits. Temperatures hot enough to physically damage pumps or motors will also damage the oil, necessitating its replacement as well.

System troubleshooting
Accurate troubleshooting requires basic gauges: a vacuum gauge, pressure gauges, a flow meter, and a temperature gauge. Always take readings at normal operating speeds and oil temperatures. It is both ineffective and potentially dangerous to attempt repair of hydraulic equipment without the correct test gauges.

The vacuum gauge should be plumbed into the inlet line at the pump port. A vacuum reading at normal engine operating speed greater than 5 in.Hg. indicates a restriction which could lead to cavitation damage. Inspect the hose, strainer, shut-off valve, and breather for the source of the restriction.

When using pressure gauges to test system pressures always start with a high pressure gauge (0–5,000 PSI) and switch to a low pressure gauge (0–500 PSI) only after confirming that the pressure is within its range. Pressure gauges can be used to adjust system relief valves, determine neutral system pressure, or diagnose pump-related problems.

Flow meters can confirm that a pump’s output flow is within specification and, when used in conjunction with a pressure gauge, test a pump’s efficiency at various pressures.

Use a temperature gauge to confirm system operating temperature. Try to keep the oil temperature under 140° F. If operating temperatures exceed 140° F, increase reservoir capacity, add a cooler, or review component selection to confirm that all components are properly sized for the system flow.

Once hydraulic system repairs have been made, or components replaced, it is of extreme importance that efforts be taken to prevent contamination. Tanks, cylinders, and hoses should be flushed. Replace filters and fill the system with new, filtered oil. Operate all valve controls, extending and retracting cylinders, then change filters again before placing the equipment back into service.
COMMON ERRORS
TYPICAL AND CHRONIC HYDRAULIC PROBLEMS

1. Systems are not adequately protected from contamination, causing excessive wear, hydraulic inefficiency, and premature failure. Contamination is still the most frequent cause of hydraulic system failure.

2. Systems often have the wrong oil, which causes oil to
   • Be replaced more often
   • Create heat from high viscosity (oil too thick) sluggishness, or from cavitation
   • Create heat from low viscosity (oil too thin), causing excessive slippage, poor efficiency, and component wear

3. System operators are not trained to recognize
   • When the system requires servicing
   • When they are damaging the system by forcing flow over relief
   • How much damage they can inflict
   • When systems should be disengaged

4. Replacement pumps are often larger in displacement than they need to be. As a result, they
   • Require higher input torque than necessary
   • Operate at less efficient speeds
   • Create more heat
   • May cause transmission torque converter slippage

5. Hydraulic lines and hoses that are too small, or are the wrong type will
   • Require additional horsepower to compensate for the pressure losses in the system
   • Create heat, which damages hoses and oil, requiring both to be replaced more often than should be necessary
   • Restrict the amount of oil which can flow without turbulence, causing cavitation, aeration, and heat
   • Collapse or burst, making the system fail
   • Create higher system neutral pressure and higher operating pressure

6. Systems that are not calibrated, and often set up improperly usually involve
   • Relief valve set either too high (not protecting components) or too low, cycling unnecessarily
   • Relief valve isolated by quick disconnect, eliminating protection
   • Incorrect circuit continuity

7. Improperly installed drivelines causing vibration, noise, seal leakage, contamination and pump shaft damage will
   • Allow dirt to invade the seal area by distorting seal
   • Allow dirt to abrade the shaft seal area, requiring shaft replacement

8. Systems operated without any oil, or with the supply valve closed.


10. System breathers become clogged or are inadequate, resulting in cavitation.
# Hydraulic Pump Troubleshooting Guide

<table>
<thead>
<tr>
<th>Condition</th>
<th>Likely Cause</th>
<th>Correction</th>
</tr>
</thead>
<tbody>
<tr>
<td>No oil flow from pump</td>
<td>No oil in reservoir</td>
<td>Fill reservoir with approved fluid</td>
</tr>
<tr>
<td></td>
<td>Closed shut-off valve.</td>
<td>Open valve</td>
</tr>
<tr>
<td></td>
<td>Air lock in pump inlet hose</td>
<td>Use compressed air to pressurize reservoir while running pump or fill inlet hose with oil from the pump end</td>
</tr>
<tr>
<td></td>
<td>Pump is wrong rotation for application</td>
<td>Replace or re-configure pump to correct rotation</td>
</tr>
<tr>
<td></td>
<td>Hoses are reversed</td>
<td>Change inlet and pressure hose locations</td>
</tr>
<tr>
<td></td>
<td>PTO not engaged</td>
<td>See IN84-03</td>
</tr>
<tr>
<td></td>
<td>Pump worn or damaged</td>
<td>Repair or replace pump</td>
</tr>
<tr>
<td>Pump will not build/hold pressure</td>
<td>Relief valve improperly set</td>
<td>Adjust relief valve to manufacturers specification</td>
</tr>
<tr>
<td></td>
<td>Relief valve stuck open</td>
<td>Remove, clean, and re-set to specification</td>
</tr>
<tr>
<td></td>
<td>Pump worn or damaged</td>
<td>Repair or replace pump</td>
</tr>
<tr>
<td>Pump is noisy</td>
<td>Aeration (air in system)</td>
<td>See oil foaming</td>
</tr>
<tr>
<td></td>
<td>Cavitation caused by excessive vacuum at the pump inlet. Test with a vacuum gauge at the inlet port. Gauge should register under 5 in.Hg. at normal operating speed.</td>
<td>Increase inlet hose size; reroute inlet hose; check for kinked or collapsed inlet hose; check for clogged reservoir breather, or strainer; inlet hose should be SAE type 100R4 hose only.</td>
</tr>
<tr>
<td>Pump leaks:</td>
<td>Dirt under seal</td>
<td>Replace seal; examine pump shaft for scoring</td>
</tr>
<tr>
<td>At shaft seal</td>
<td>Damaged seal or pump body</td>
<td>Replace seal or body section</td>
</tr>
<tr>
<td></td>
<td>Improperly fitted seal</td>
<td>Replace seal</td>
</tr>
<tr>
<td>At body section</td>
<td>Damaged O’Ring or body</td>
<td>Replace O-Ring or body section</td>
</tr>
<tr>
<td></td>
<td>Improperly torqued bolts</td>
<td>Torque to specification</td>
</tr>
<tr>
<td>At pump port</td>
<td>Loose fitting</td>
<td>Tighten fitting</td>
</tr>
<tr>
<td>*DO NOT USE TEFLON TAPE ON PIPE THREAD FITTINGS</td>
<td>Damaged fitting</td>
<td>Replace fitting</td>
</tr>
<tr>
<td></td>
<td>Damaged pump body</td>
<td>Replace body section</td>
</tr>
<tr>
<td>Pump is hot (oil temperature should not exceed 140° F [60° C])</td>
<td>Low oil level</td>
<td>Fill reservoir</td>
</tr>
<tr>
<td></td>
<td>Reservoir too small</td>
<td>Increase reservoir size; a cooler may be required</td>
</tr>
<tr>
<td></td>
<td>Dirty oil</td>
<td>Replace oil and filter</td>
</tr>
<tr>
<td></td>
<td>Relief valve stuck open</td>
<td>Remove, clean, and re-set; adjust relief valve to manufacturer’s specification</td>
</tr>
<tr>
<td></td>
<td>Relief valve improperly set</td>
<td>Review application</td>
</tr>
<tr>
<td></td>
<td>Pump too large for application</td>
<td>Replace with correct model</td>
</tr>
<tr>
<td></td>
<td>Undersized system component</td>
<td>Review application; replace with correct model</td>
</tr>
<tr>
<td></td>
<td>Improper weight oil</td>
<td>Replace with correct oil</td>
</tr>
<tr>
<td>Oil foaming</td>
<td>Low oil level</td>
<td>Fill reservoir</td>
</tr>
<tr>
<td></td>
<td>Loose inlet fitting</td>
<td>Tighten fitting</td>
</tr>
<tr>
<td></td>
<td>Damaged shaft seal</td>
<td>Replace seal</td>
</tr>
<tr>
<td></td>
<td>Leak in inlet hose</td>
<td>Replace hose</td>
</tr>
<tr>
<td></td>
<td>Improper tank baffle</td>
<td>Install baffle or diffuser</td>
</tr>
</tbody>
</table>
### SECTION 14:
**CONVERSION CHARTS, EQUIVALENTS, AND FORMULAS**

#### CONVERSION CHART
From English Units (U.S.) to Système International (Metric)

<table>
<thead>
<tr>
<th>From</th>
<th>To</th>
<th>Multiply By</th>
<th>or</th>
<th>Divide By</th>
</tr>
</thead>
<tbody>
<tr>
<td>cu.in. (in³)</td>
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<tr>
<td>cu.in. (in³)</td>
<td>Liters</td>
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<td>61.02</td>
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<tr>
<td>Pounds Feet</td>
<td>Newton meters (Nm)</td>
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<td>Gallons (U.S.)</td>
<td>Liters</td>
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<td>cu.in. (in³)</td>
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</tr>
<tr>
<td>Horsepower</td>
<td>BTU</td>
<td>2545.0</td>
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<td>Horsepower</td>
<td>WATTS</td>
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<tr>
<td>Horsepower</td>
<td>kW</td>
<td>0.7457</td>
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<td>1.341</td>
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<tr>
<td>PSI (pounds/in²)</td>
<td>BAR</td>
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<tr>
<td>PSI (pounds/in²)</td>
<td>Kilopascal (KPa)</td>
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<tr>
<td>Pound</td>
<td>Kilogram</td>
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<td></td>
<td>2.2046</td>
</tr>
<tr>
<td>Inch</td>
<td>Millimeter (mm)</td>
<td>25.4</td>
<td></td>
<td>0.03937</td>
</tr>
<tr>
<td>Mile</td>
<td>Kilometer (km)</td>
<td>1.6093</td>
<td></td>
<td>0.6214</td>
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</tbody>
</table>

#### ABBREVIATION EQUIVALENTS

<table>
<thead>
<tr>
<th>A = Area of circle (sq.in.)</th>
<th>Ext = Extension</th>
<th>kW = Kilowatts</th>
<th>r = Radius</th>
</tr>
</thead>
<tbody>
<tr>
<td>BAR = Unit of pressure</td>
<td>F = Fahrenheit</td>
<td>lbs.ft. = Force to produce torque</td>
<td>RPM = Revolutions per minute</td>
</tr>
<tr>
<td>β = Beta ratio</td>
<td>ft.lb. = A unit of work</td>
<td>Li = Length (inches)</td>
<td>sq.in. = square inches</td>
</tr>
<tr>
<td>cc. = Cubic centimeters</td>
<td>F = Force</td>
<td>L = Liters</td>
<td>STL = Shaft torque limitation</td>
</tr>
<tr>
<td>C = Celsius</td>
<td>gal. = Gallons</td>
<td>µm = Micrometers</td>
<td>Ta = Torque accelerating</td>
</tr>
<tr>
<td>CID = Cubic inch displacement</td>
<td>GPM = Gallons per minute</td>
<td>µ = Microns</td>
<td>Tc = Torque continuous</td>
</tr>
<tr>
<td>CIR = Cubic inches/revolution</td>
<td>HP = Horsepower</td>
<td>ml = Milliliter</td>
<td>T = Torque</td>
</tr>
<tr>
<td>cu.in. = Cubic inches</td>
<td>Hyd = Hydraulic</td>
<td>mm = Millimeters</td>
<td>TJA = True joint angle</td>
</tr>
<tr>
<td>Cyl. = Cylinder</td>
<td>in. = Inches</td>
<td>Min. = Minutes</td>
<td>Ts = Torque starting</td>
</tr>
<tr>
<td>Δ = Delta (change)</td>
<td>in.lb. = Inches per pound</td>
<td>Nm = Newton meters</td>
<td>V = Velocity</td>
</tr>
<tr>
<td>ΔP = Delta-P or parasitic pressure</td>
<td>in.Hg. = Inches of mercury</td>
<td>OA = Operating</td>
<td>Vol. = Volume</td>
</tr>
<tr>
<td>d = Diameter</td>
<td>K = HP per foot of PLV</td>
<td>π = 3.1416 (pi)</td>
<td>VE = Volumetric efficiency</td>
</tr>
<tr>
<td>Di = Depth (inches)</td>
<td>Kg. = Kilograms</td>
<td>PPM = Parts Per Million</td>
<td>Wi = Width (inches)</td>
</tr>
<tr>
<td>E or EFF = Efficiency</td>
<td>km = Kilometer</td>
<td>PLV = Pitch Line Velocity</td>
<td></td>
</tr>
</tbody>
</table>
**FORMULAS FOR CALCULATOR USE**

The following formulas will assist in calculating specific requirements to help determine the appropriate products to pair for a successful hydraulic system. Formulas include those to solve horsepower, torque, engine speed, and so forth.

<table>
<thead>
<tr>
<th>To Solve For</th>
<th>Calculator Entry</th>
</tr>
</thead>
<tbody>
<tr>
<td>PTO Output Speed (RPM)</td>
<td>PTO RPM = Engine RPM × PTO%</td>
</tr>
<tr>
<td>Required Engine Speed (RPM)</td>
<td>Engine RPM = Desired PTO RPM ÷ PTO%</td>
</tr>
<tr>
<td>Horsepower (HP)</td>
<td>HP = T (ft.lbs.) ÷ RPM × 5252</td>
</tr>
<tr>
<td>Torque (ft.lbs.)</td>
<td>T = HP × 5252 × RPM ÷ 5252</td>
</tr>
<tr>
<td>Area of a Circle</td>
<td>A = πr² or A = d² × .7854</td>
</tr>
<tr>
<td>Volume of a Cylinder (gal.)</td>
<td>V = πr² × Li ÷ 231 OR d² × .7854 × Li ÷ 231</td>
</tr>
<tr>
<td>Force of a Cylinder (lb.)</td>
<td>F = A (sq.in.) × PSI</td>
</tr>
<tr>
<td>Cylinder Extension (inches/second)</td>
<td>Ext. Rate = GPM × 4.9 ÷ d² (in.)</td>
</tr>
<tr>
<td>Cylinder Extension (seconds to extend)</td>
<td>Ext. Time = Cyl. Volume (cu.in.) × .26 ÷ GPM</td>
</tr>
<tr>
<td>Volume of a Reservoir (rectangular, gal.)</td>
<td>Vol = Li × Wi × Di ÷ 231</td>
</tr>
<tr>
<td>Volume of a Reservoir (round, gal.)</td>
<td>Vol = πr² × Li ÷ 231 OR d² × .7854 × Li ÷ 231</td>
</tr>
<tr>
<td>Pump Output Horsepower (HP)</td>
<td>HP = GPM × PSI ÷ 1714</td>
</tr>
<tr>
<td>Pump Input Horsepower (HP)</td>
<td>HP = GPM × PSI ÷ 1714 ÷ E</td>
</tr>
<tr>
<td>Pump Input Torque (ft.lbs.)</td>
<td>T = CID × PSI ÷ 24π</td>
</tr>
<tr>
<td>Pump Output Flow (GPM)</td>
<td>GPM = CIR × RPM ÷ 231 × E</td>
</tr>
<tr>
<td>Pump Input Speed (RPM)</td>
<td>RPM = GPM × 231 ÷ CIR ÷ E</td>
</tr>
<tr>
<td>Displacement of Pump (CIR)</td>
<td>CIR = GPM × 231 ÷ RPM ÷ E</td>
</tr>
<tr>
<td>Flow in GPM Using PTO</td>
<td>GPM = Engine RPM × PTO% ÷ 231 ÷ E</td>
</tr>
<tr>
<td>Velocity of Oil (ft/sec)</td>
<td>V = GPM × .3208 ÷ A (sq.in.)</td>
</tr>
<tr>
<td>Pressure Drop Through an Orifice (Psi)</td>
<td>ΔP = .025 × GPM² ÷ d⁵ (in.)</td>
</tr>
<tr>
<td>Heat Rise in Degrees F</td>
<td>ΔFº = HP × 746 × Inefficiency ÷ Min. ÷ Gal. in System ÷ 60</td>
</tr>
</tbody>
</table>

**NOTE:** The following hydraulic motor formulas are calculated in inch pounds (in.lbs.) rather than foot pounds (ft.lbs.). To convert to ft.lbs., divide by 12.

**MOTOR OUTPUT TORQUE**

| Continuous                        | Tc = GPM × PSI × 36.77 ÷ RPM                                                      |
|                                   | OR Tc = CID × PSI ÷ 2π                                                          |
|                                   | OR Tc = HP × 63025 ÷ RPM                                                        |
| Starting                          | Ts = Tc × 1.3                                                                    |
| Accelerating                      | Ta = Tc × 1.1                                                                   |
| Motor Working Pressure            | PSI = T × 2π ÷ CIR ÷ E                                                          |
| Motor RPM                         | RPM = GPM × 231 ÷ CIR                                                           |

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